

Jigsaw Image Mosaics

Kim and Pellacini, Cornell 2004

Presented by Kacper Wysocki

Introduction

- Fill arbitrary container compactly with arbitrarily-shaped tiles of similar color
- Deform tiles slightly for effect



Figure 1 from Kim and Pellacini

Motivation

- Arcimboldo, Renaissance Italian Painter



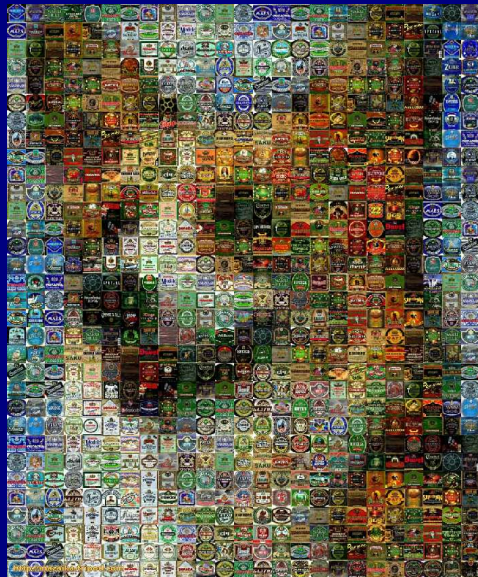
Vertemnus



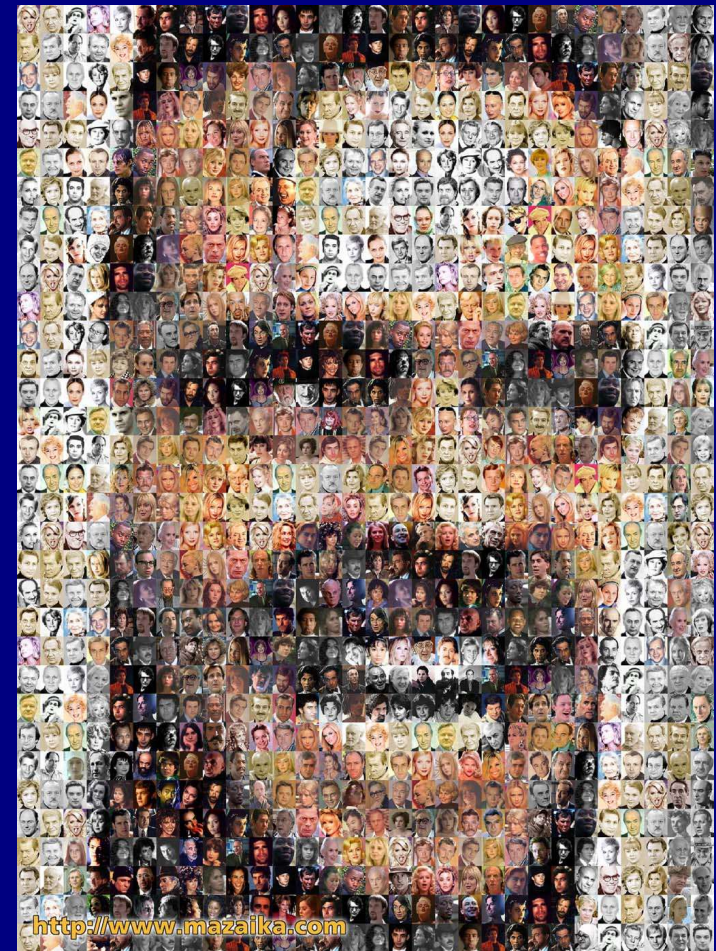
Seasons

Related work

- *Photomosaics*
 - Finkelstein and Range '98
 - Silvers and Hawley '97
 - Images in rectangular grid



Dog of beer



Shining shot composed of various actors

Related work

- *Simulated Decorative Mosaics*
 - Hausner '01
 - Align square tiles with varying orientations to preserve edges and maximise coverage

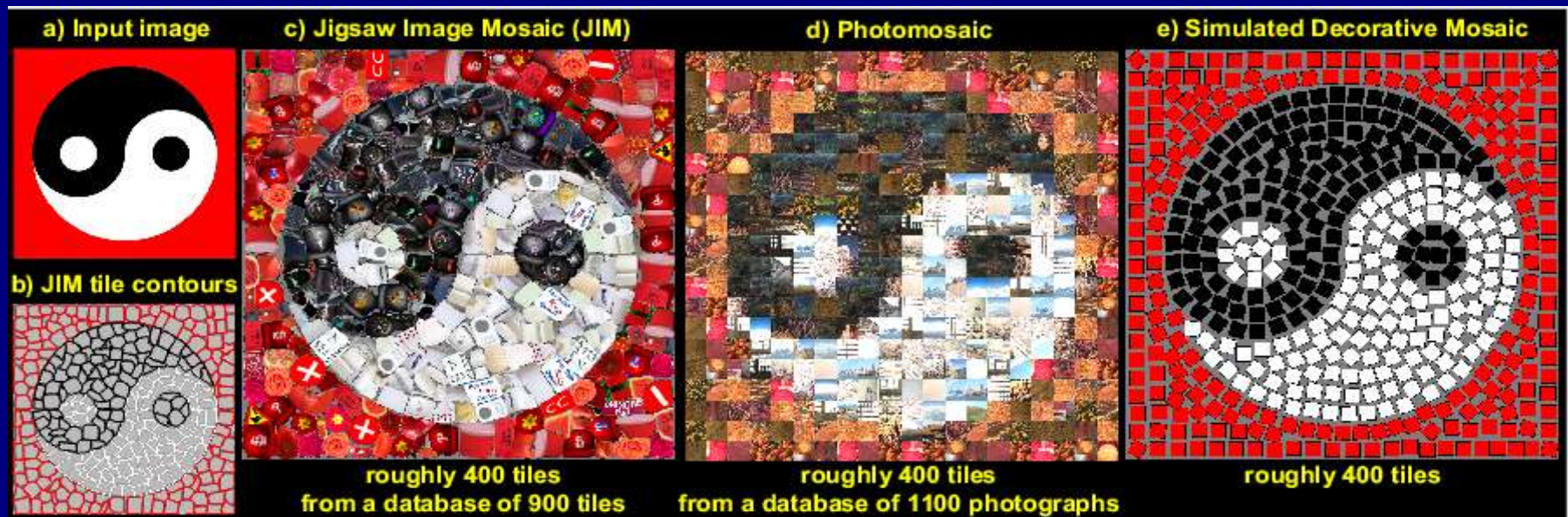


Figure 2 from paper

Related work

- *Escherization*

- Kaplan and Salesin '01



Regular dog tilings

Overview

- Packing problem is NP-hard
- Energy-based framework generalizes known algorithms
- Energy-minimization algorithm for solving mosaicing 'soft' packing problem

Preparing inputs

- Input:
 - Container image
 - Set of arbitrarily shaped tiles
 - Shape of tiles and container as polygons
- Preprocessing:
 - Automatic segmentation
 - Segment input image to retain edges

Mosaicing Energy Framework

- *Tile configuration*: subset of input tiles + transformations
- **JIM** when minimizes energy function

$$E = w_C \cdot E_C + w_G \cdot E_G + w_O \cdot E_O + w_D \cdot E_D$$

C – color difference

G – gap

O – overlap

D – deformation

Can make Photomosaics and Simulated Decorative Mosaics

Energy Evaluation

$$E = w_C \cdot E_C + w_G \cdot E_G + w_O \cdot E_O + w_D \cdot E_D$$

- E_C – L-squared color difference
- E_G – gap – spring energy formula
- E_O – overlap
- E_D - deformation

$$E_D = \frac{1}{2} \sum_{i=1}^k \int_0^1 \alpha |D_i''(s) - T_i''(s)|^2 + \beta |D_i'''(s) - T_i'''(s)|^2 ds$$

Figure 3 from Kim and Pellacini

Energy Evaluation

$$E = w_C \cdot E_C + w_G \cdot E_G + w_O \cdot E_O + w_D \cdot E_D$$

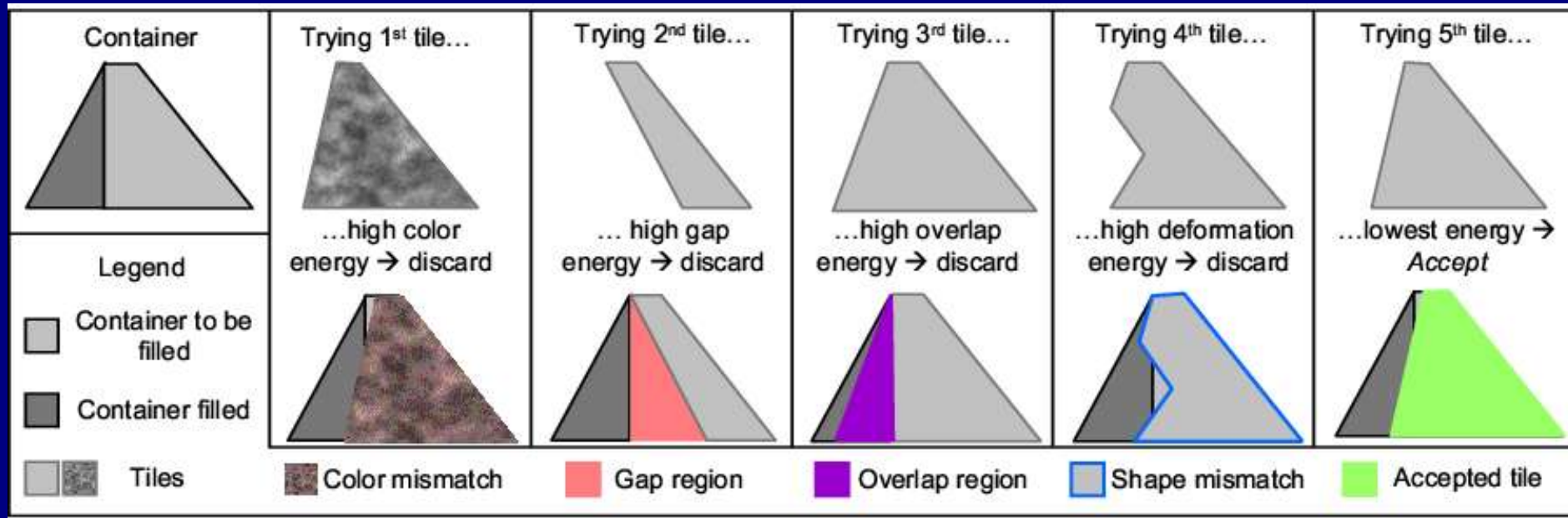


Figure 3 from Kim and Pellacini

Basic Algorithm

- Three phases
 - Packing
 - Refine and deform
 - Assemble and adjust

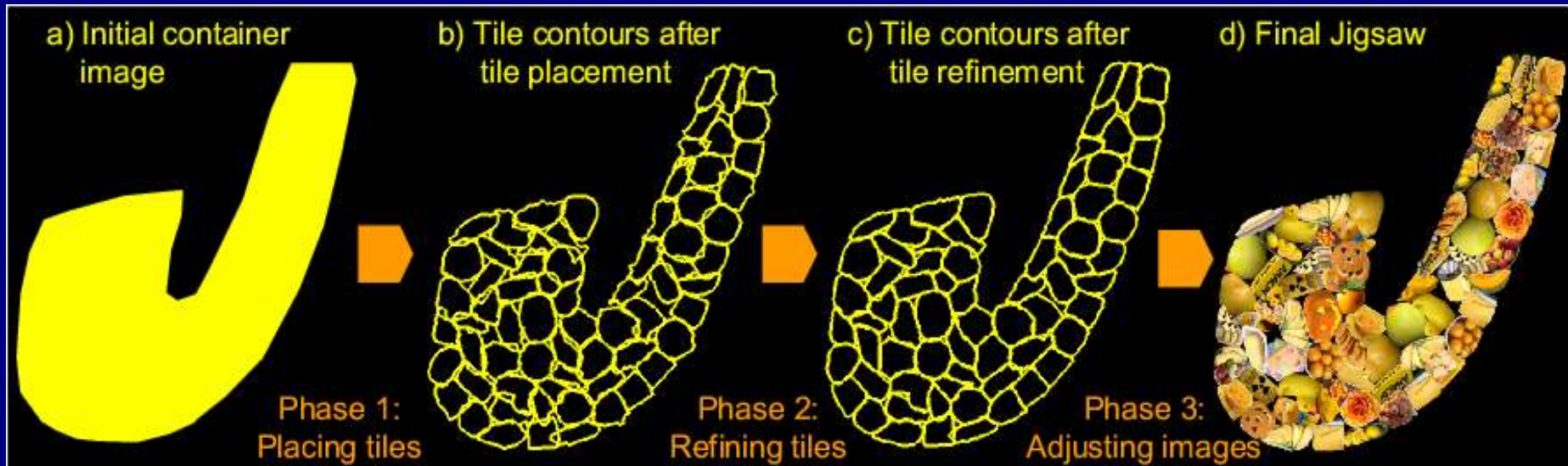


Figure 4 from Kim and Pellacini

Basic Algorithm

■ Packing

- Ignore deformations
- Search database, one tile at a time
- Position and location
- Backtracking
- New container = old container – shape of tile

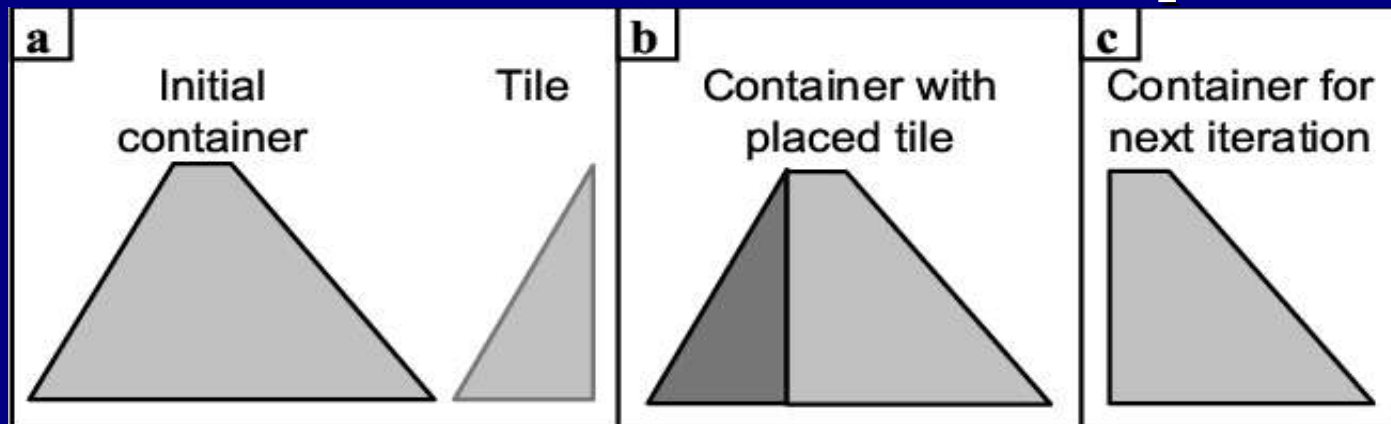


Figure 5 from Kim and Pellacini

Backtracking

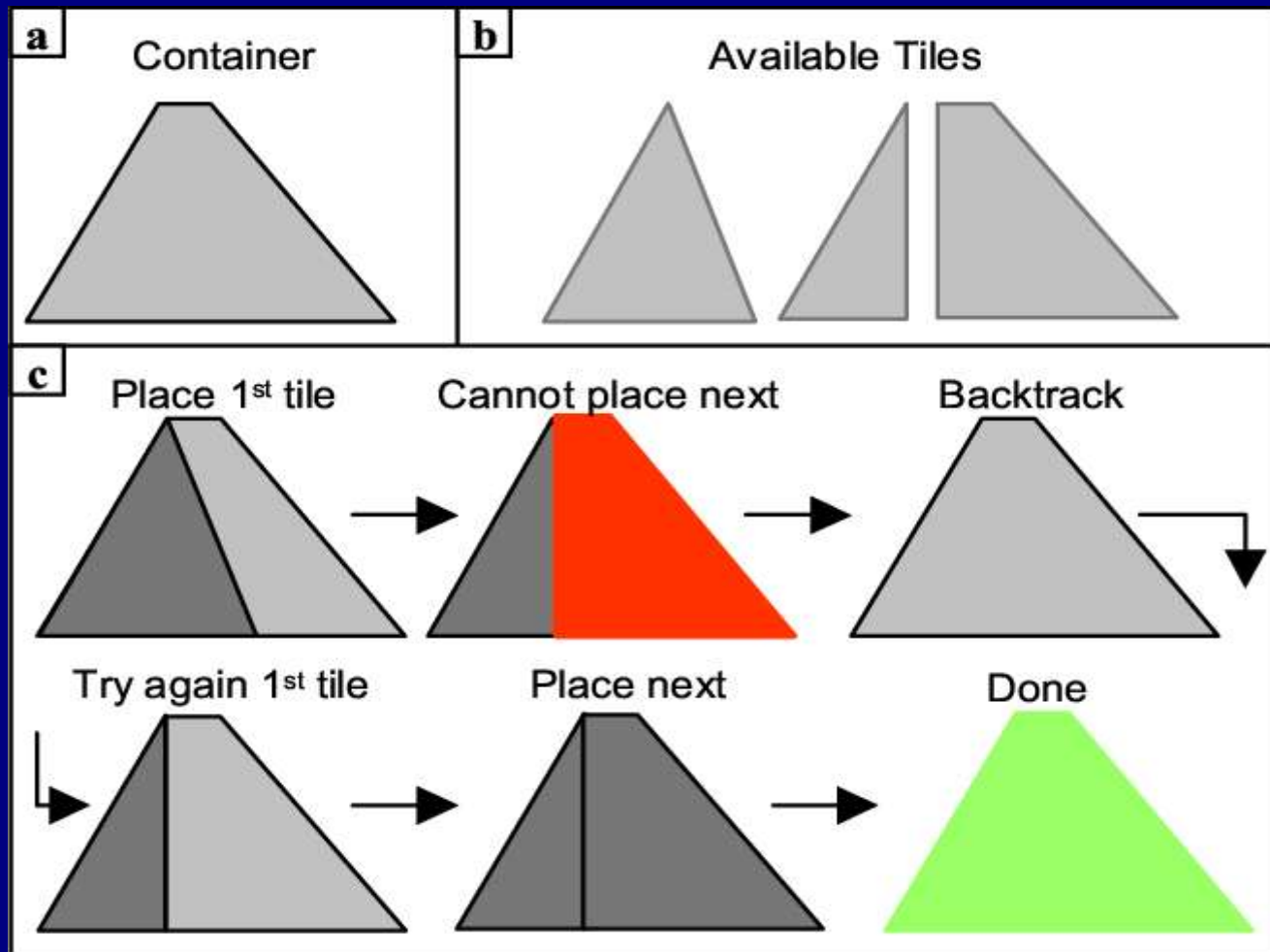


Figure 6 from Kim and Pellacini

Basic Algorithm

■ Refine

- Deform to reduce gaps and overlaps
- To minimize energy, solve

$$w_c \cdot \nabla E_C + w_G \cdot \nabla E_G + w_O \nabla E_O + w_D \cdot \nabla E_D = 0$$

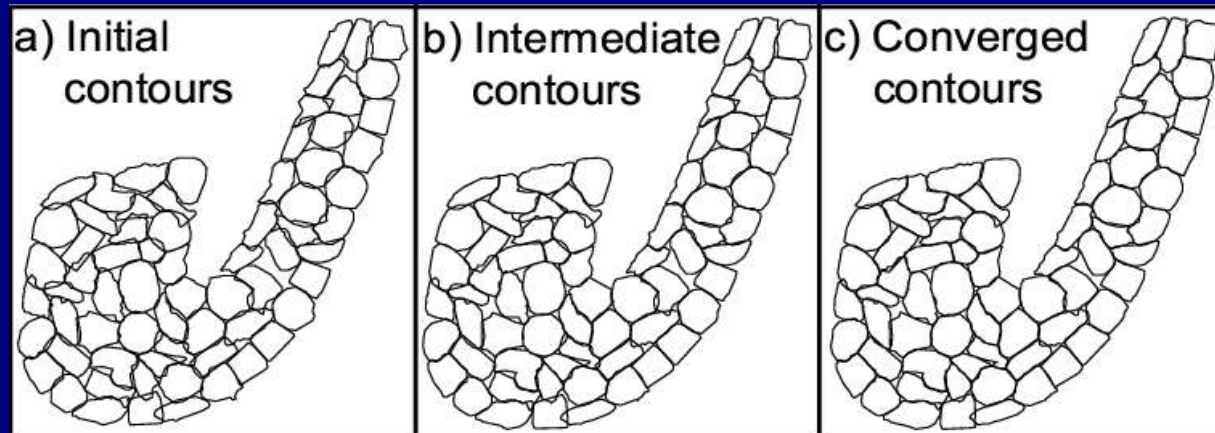


Figure 7 from Kim and Pellacini

Basic Algorithm

■ Refine

- Use active contours to solve

$$w_c \cdot \nabla E_C + w_G \cdot \nabla E_G + w_O \nabla E_O + w_D \cdot \nabla E_D = 0$$

∇E_C is close to 0

$\nabla E_O = 2d \cdot n$ or gap, shrink/expand

$$\nabla E_D = \alpha(D_i''(s) - T_i''(s)) + \beta(D_i'''(s) - T_i'''(s))$$

Optimizations

■ Complexity

$$O(V_{tile} \cdot N_{tile} \cdot V_{container} \cdot N_{tilesIn} \cdot (1 + b))$$

■ We can improve this

- Tile placement
- Branch-and-bound with lookahead
- Container cleanup
- Geometric hashing

Optimizations

■ Tile placement

- Smarter – easier after placement
- Guess container after 'average' tile
- Achieved by constructing Centroidal Voronoi Diagram

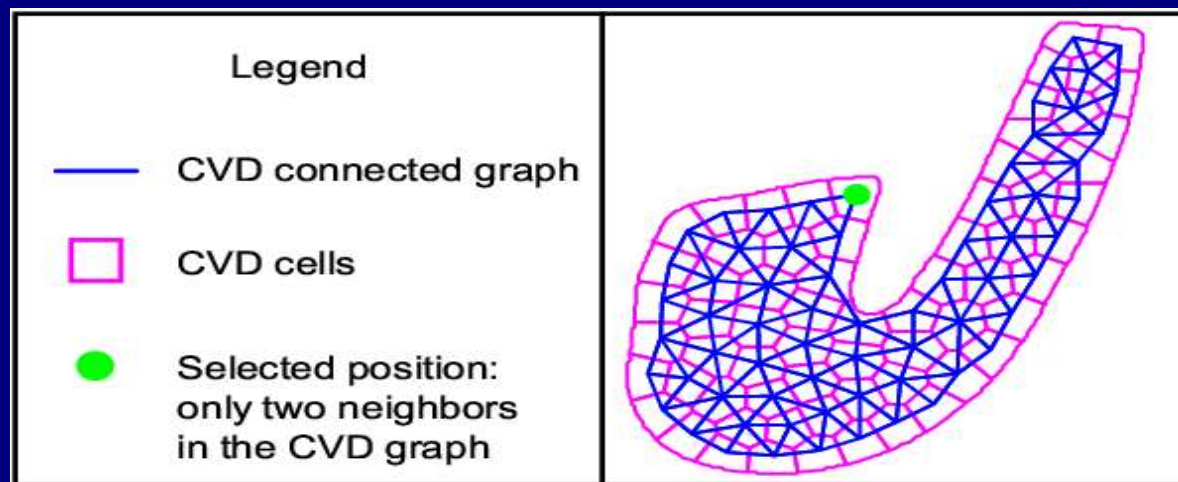


Figure 8 from Kim and Pellacini

Optimizations

- Branch-and-bound with look-ahead
 - Penalize tiles that make filling more difficult
 - Add term to energy equation:

$$\begin{aligned} E &= w_G \cdot E_G + w_O \cdot E_O + w_C \cdot E_C + w_{LA} \cdot E_{LA} \\ E_{LA} &= w_A \cdot area + (1 - w_A) \cdot length^2 \end{aligned}$$

Optimizations

- Container cleanup
 - After update, there are jagged or disjoint edges in container
 - Separate and consider as gaps
 - How does this help?

Optimizations

- Geometric hashing
 - Match geometric features against database
 - Find a set of tiles, evaluate energy formula
 - Preprocessing
 - Grid of squares in plane
 - If shape crosses square, add to entry
 - Place tiles in all orientations in grid
 - Packing stage
 - Register container boundry to hash table
 - For every (tile,orientation) cast vote

Optimizations

■ Geometric hashing

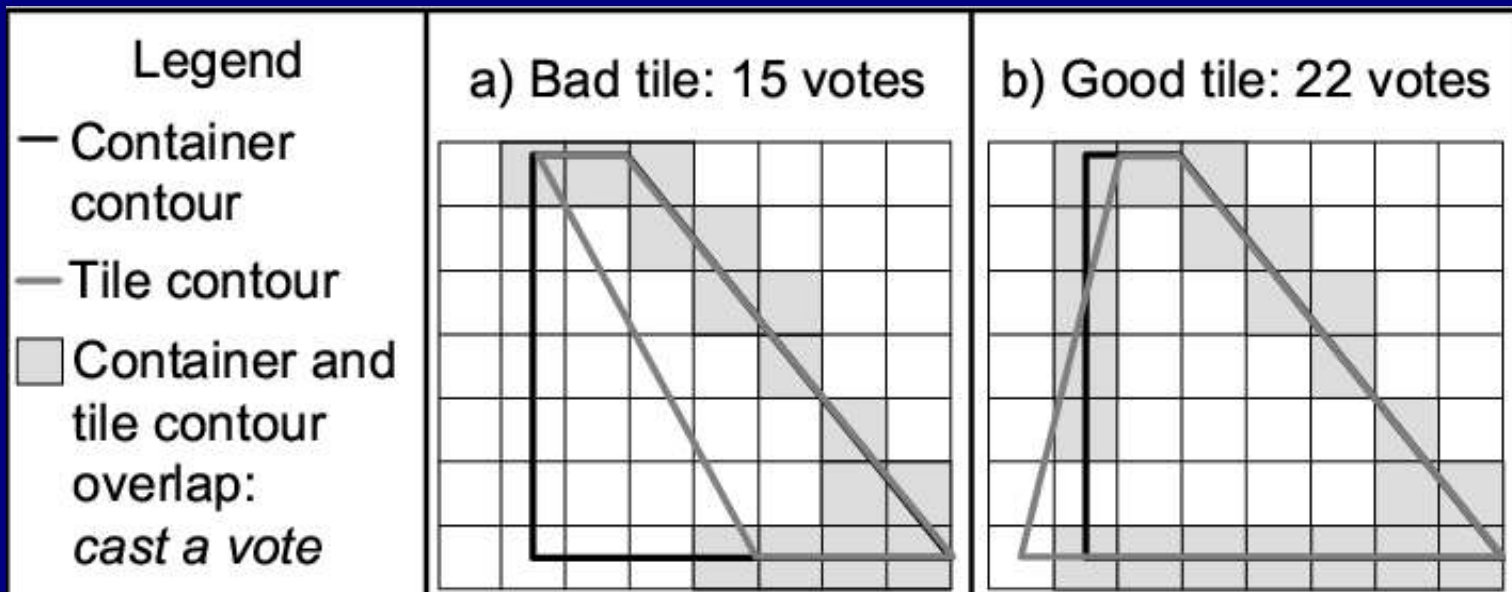


Figure 9 from Kim and Pellacini

■ How does this help?

Conclusion

- Energy-based framework for mosaicing problems generalizing existing algorithms
- Jigsaw Image Mosaic
- 'soft' packing for texture synthesis and product manufacturing
- Some results:
 - 900 tiles
 - 8x size variations in tiles
 - Process took from 10 minutes to 2 hours

Future work

- Bounds on energy hard to prove
- 3D mosaics for surface and volume
- Video mosaics – Klein et al.



Figure 10 from Kim and Pellacini



Figure 11 from Kim and Pellacini



Figure 12 from Kim and Pellacini

McGill COMP-767 Winter 2005

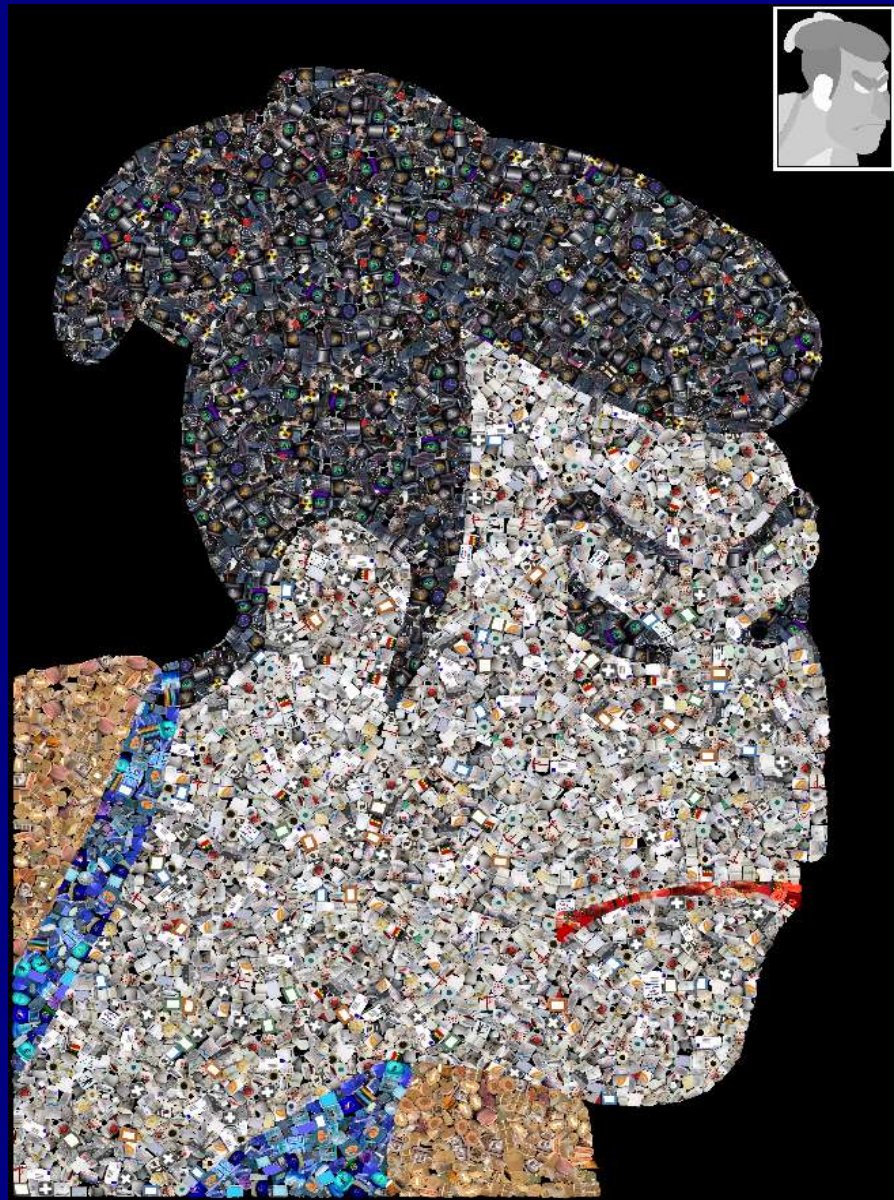


Figure 13 from Kim and Pellacini