

# **Compiler Design**

## **An Introduction to Equality Saturation and Its Applications**

*March 25, 2026*

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**McGill**

# About Me



- Undergrad in SWE (2020–2024)
- Summer research in CASL Lab (2024)
- MSc in CASL Lab (2025)
- Fast-track to PhD in CASL Lab (2026–)
- Equality saturation in production compilers
- [azizzayed.com](http://azizzayed.com)

# Outline

Compiler Optimization

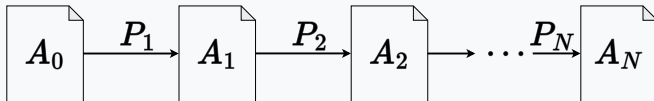
Equality Saturation

Case Studies

Applications

# Pass Sequences

An optimizer performs a sequence of passes (a.k.a. rewrites, transformations) on a program to improve its performance.



# Optimization Passes

- Constant folding
- Dead code elimination
- Common subexpression elimination
- Loop unrolling
- Loop fusion
- Loop tiling
- Loop vectorization

# Optimization Passes

- Constant folding
- Dead code elimination
- Common subexpression elimination

## Before

```
int arr[2 * 50];  
int x = 3 * (2 + 7);
```

## After Constant Folding

```
int arr[100];  
int x = 27;
```

# Optimization Passes

- Constant folding
- Dead code elimination
- Common subexpression elimination

## Before

```
int debug = 0;
if (debug)
    log("debug"); // never runs
x = compute();
```

## After Dead Code Elimination

```
x = compute();
```

# Optimization Passes

- Constant folding
- Dead code elimination
- Common subexpression elimination

## Before

```
a = x * y + z;  
b = x * y - z;
```

## After CSE

```
t = x * y; // computed once  
a = t + z;  
b = t - z;
```

# Optimization Passes

## Before

```
for (i = 0; i < 4; i++)  
  a[i] = b[i] + c[i];
```

## After Loop Unrolling

```
a[0] = b[0] + c[0];  
a[1] = b[1] + c[1];  
a[2] = b[2] + c[2];  
a[3] = b[3] + c[3];
```

- Loop unrolling
- Loop fusion
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- Loop vectorization

# Optimization Passes

## Before

```
for (i = 0; i < n; i++)  
  a[i] = b[i];  
for (i = 0; i < n; i++)  
  c[i] = a[i];
```

## After Loop Fusion

```
for (i = 0; i < n; i++) {  
  a[i] = b[i];  
  c[i] = a[i];  
}
```

- Loop unrolling
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# Optimization Passes

## Before

```
int N = 1024; // matrix size
for (i = 0; i < N; i++)
  for (j = 0; j < N; j++)
    C[i][j] += A[i][j];
```

## After Loop Tiling

```
int N = 1024; // matrix size
int T = 32; // tile size
for (ii=0; ii<N; ii+=T)
  for (jj=0; jj<N; jj+=T)
    for (i=ii; i<ii+T; i++)
      for (j=jj; j<jj+T; j++)
        C[i][j] += A[i][j];
```

- Loop unrolling
- Loop fusion
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- Loop vectorization

# Optimization Passes

## Before

```
for (i = 0; i < n; i++)  
  c[i] = a[i] + b[i];
```

## After Loop Vectorization

```
for (i = 0; i < n; i += 4) {  
  va = _mm_load_ps(&a[i]);  
  vb = _mm_load_ps(&b[i]);  
  _mm_store_ps(&c[i],  
              _mm_add_ps(va, vb));  
}
```

- Loop unrolling
- Loop fusion
- Loop tiling
- Loop vectorization

# Phase Ordering Problem

The order in which passes are applied matters. Applying passes in the wrong order may block further applicable rules, missing the global optimum [1].

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Rewrite rules:

- $P_1.$   $\underline{xy/z} \rightarrow x(y/z)$
- $P_2.$   $\underline{x \cdot 2} \rightarrow x \lll 1$
- $P_3.$   $\underline{xy} \rightarrow yx$
- $P_4.$   $\underline{x/x} \rightarrow 1$
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- $(a \cdot 2)/2$

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- $(a \cdot 2)/2 \xrightarrow{P_1} a \cdot (2/2)$

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  - $(a \cdot 2)/2 \xrightarrow{P_1} a \cdot (2/2) \xrightarrow{P_4} a \cdot 1 \xrightarrow{P_5} a$
1. The optimizer may get stuck in a local optimum if it applies transformations out-of-order (e.g.  $P_2$  before  $P_1$ ).
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# Outline

Compiler Optimization

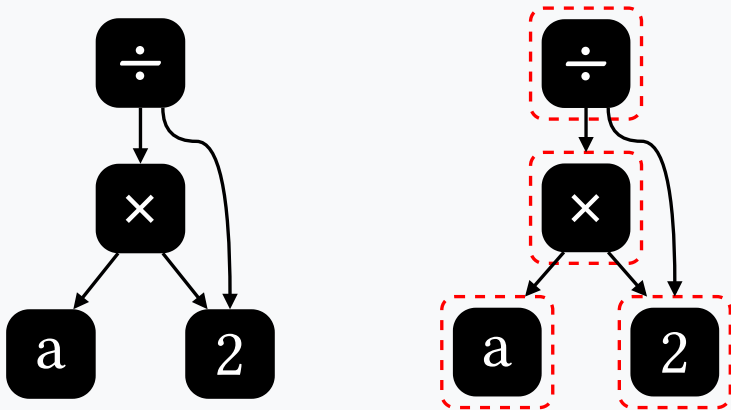
**Equality Saturation**

Case Studies

Applications

# E-Graphs

An e-graph stores many equivalent forms of an expression [1].

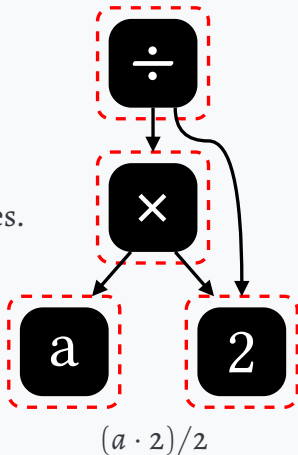


$$(a \cdot 2) / 2$$

# E-Graphs

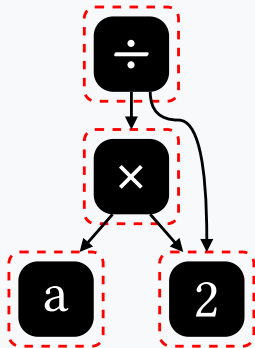
An **e-graph** stores many equivalent forms of an expression [1].

1. **e-node** : Operation node.
2. **e-class** : Set of equivalent e-nodes.
3. **e-graph**: Set of e-classes.



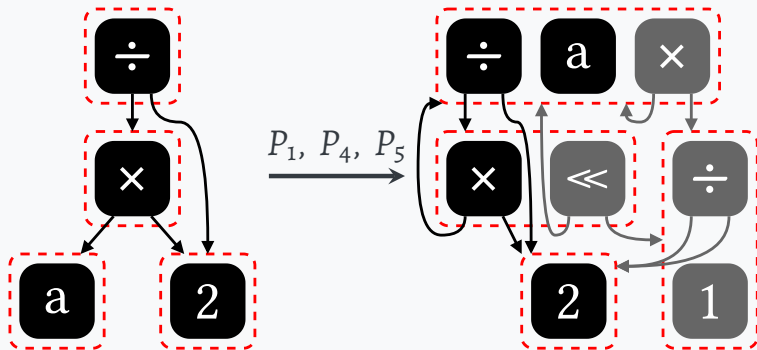
# Apply Rewrite Rules to an E-Graph

- $P_1.$   $xy/z \rightarrow x(y/z)$
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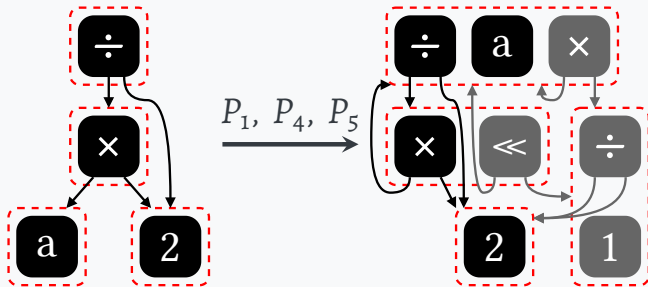


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# Equality Saturation



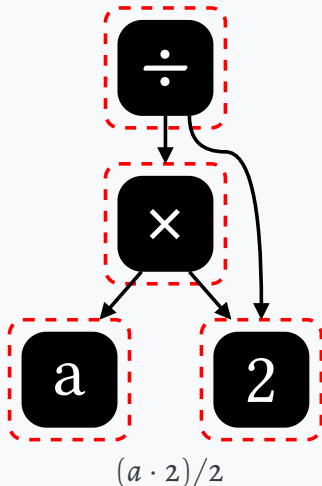
Problems are solved:

1. The global optimum is found by extracting the optimal expression from the e-graph via a cost model.
2. The original and intermediate versions of the program are preserved in the e-graph.

# Equality Saturation

Equality saturation steps [1]:

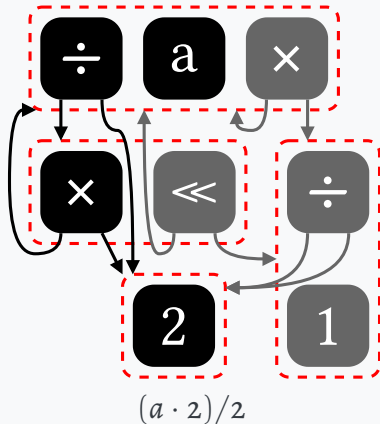
1. Build an **e-graph** of  $(a \cdot 2)/2$ .
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# Tree Cost Extraction

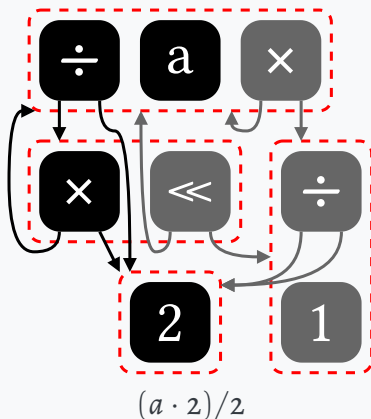
We define a **cost model**  $C$  to extract the optimal expression from the saturated e-graph.

$$C(n) = \begin{cases} 10 & \text{if } n \text{ is } \times \\ 20 & \text{if } n \text{ is } \div \\ 5 & \text{if } n \text{ is } \ll \\ 1 & \text{else} \end{cases}$$

$$C(E) = \min_{n \in E} C(T_n)$$

$$C(T_n) = C(n) + \sum_{n \rightarrow E} C(E)$$

Where  $n$  is an e-node,  $E$  is an e-class,  $T_n$  is the tree rooted at e-node  $n$ , and  $\rightarrow$  is an e-node to e-class edge.



# Tree Cost Extraction

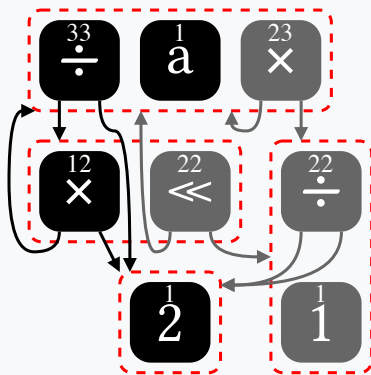
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$$(a \cdot 2)/2 \rightarrow a$$

# Outline

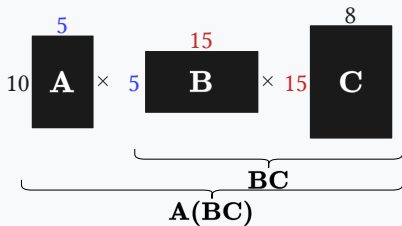
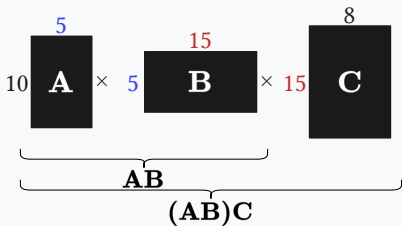
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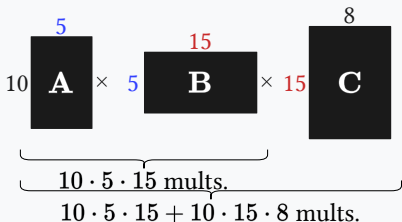
# MatMul Associativity [2]



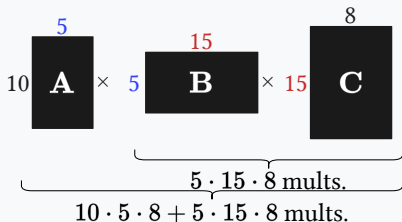
$$(AB)C = A(BC)$$

How do we find out which one is more efficient?

# The Order of Operations Matters



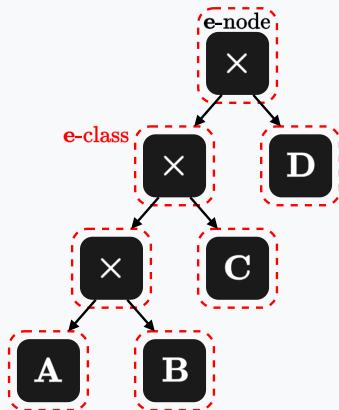
cost  $(AB)C = 1950$   
multiplications.



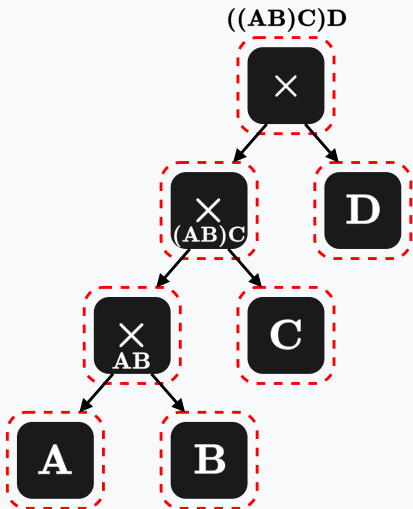
cost  $A(BC) = 1000$   
multiplications.

# Equality Saturation for $((AB) C) D$

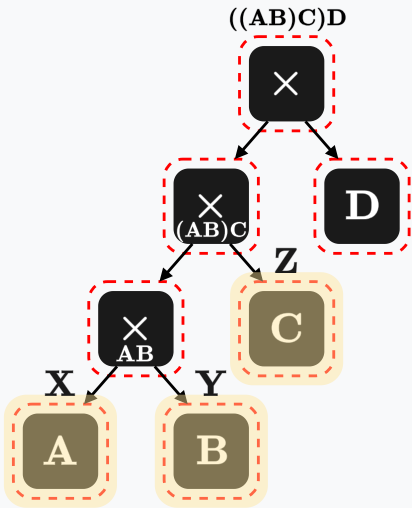
1. Build an **e-graph** of  $((AB) C) D$ .
2. Apply the rewrite rule  $(XY) Z \Leftrightarrow X (YZ)$  to the e-graph until a fixed-point.
3. Extract the optimized expression via a cost model.



## 2. Apply the Rewrite $(XY)Z \Leftrightarrow X(YZ)$

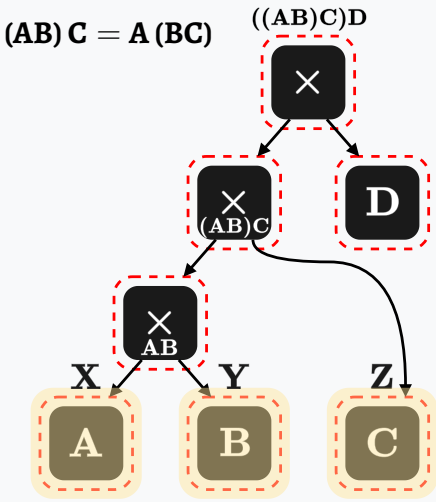
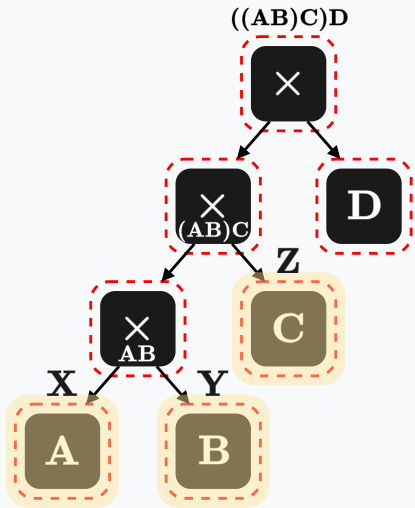


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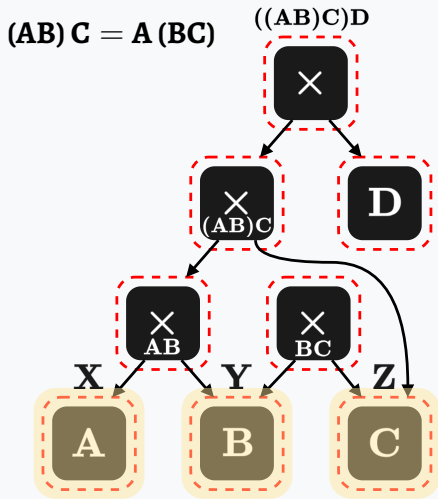
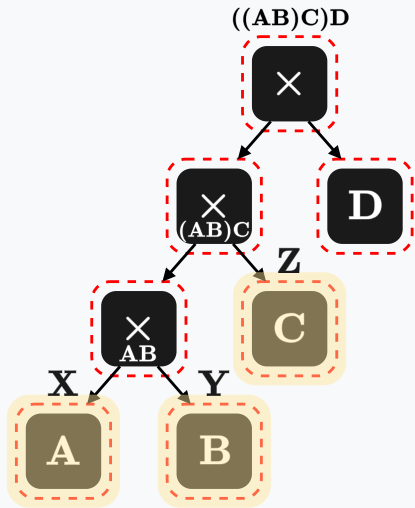


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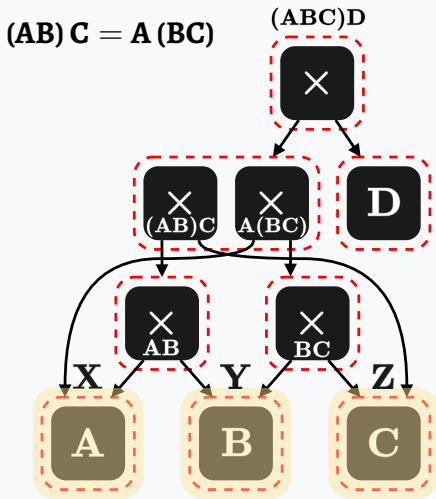
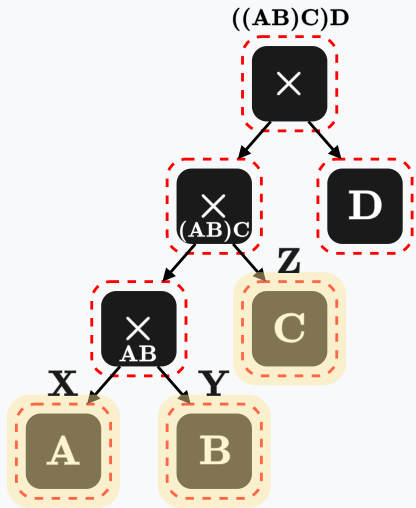
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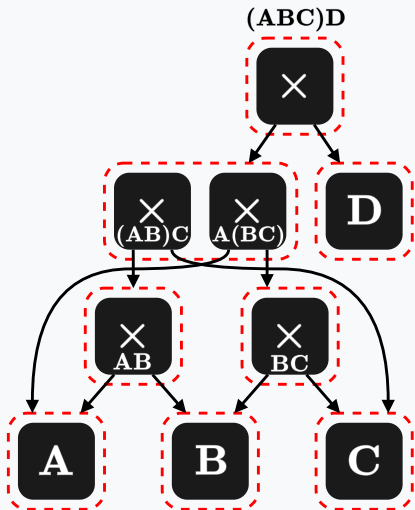
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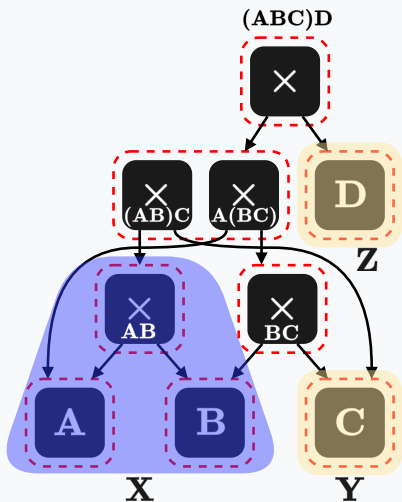


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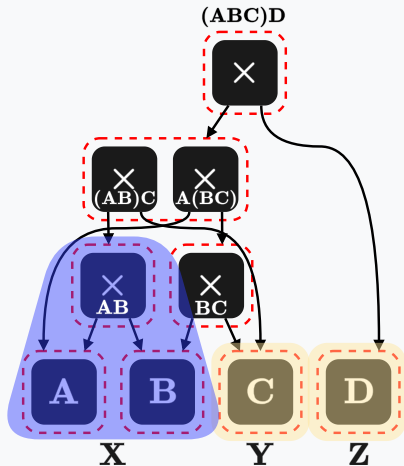
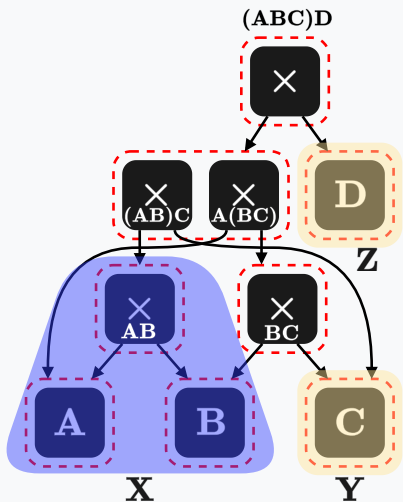
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$$((AB) C) D = (AB) (CD)$$



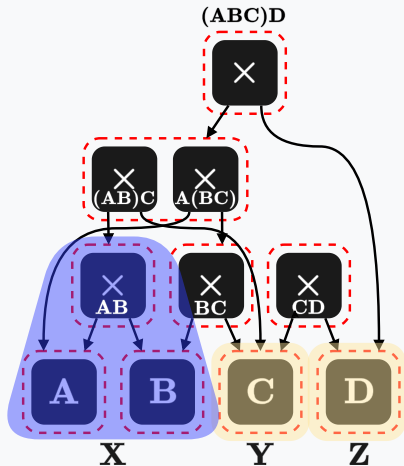
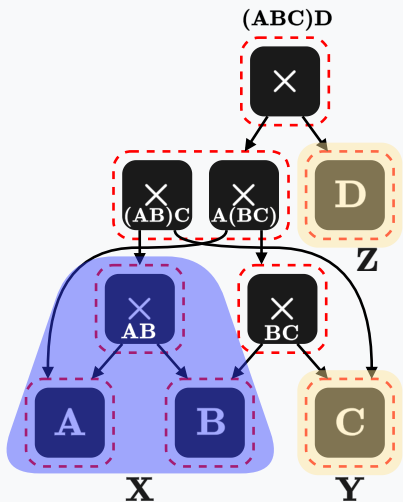
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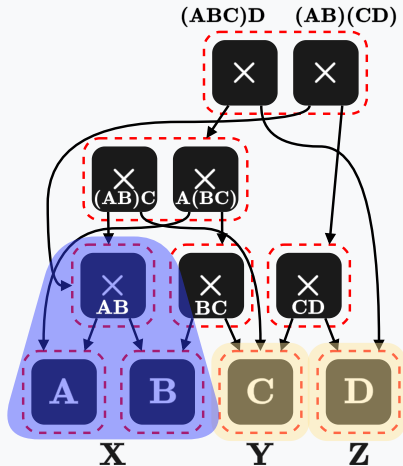
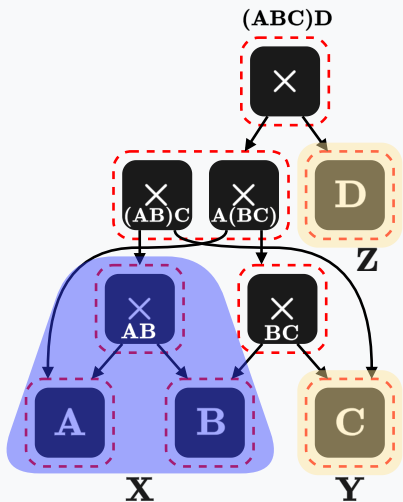
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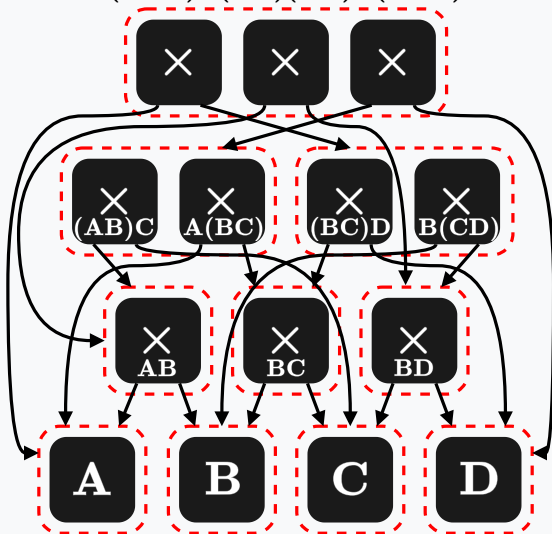
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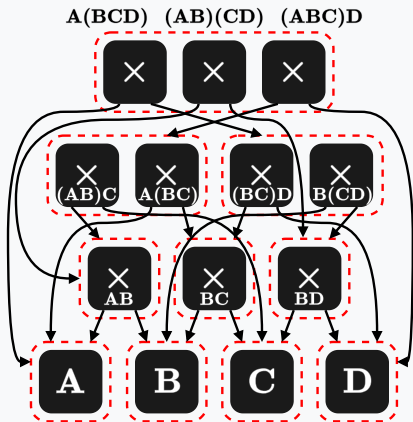


# Final E-Graph After Saturation

$A(BCD)$   $(AB)(CD)$   $(ABC)D$



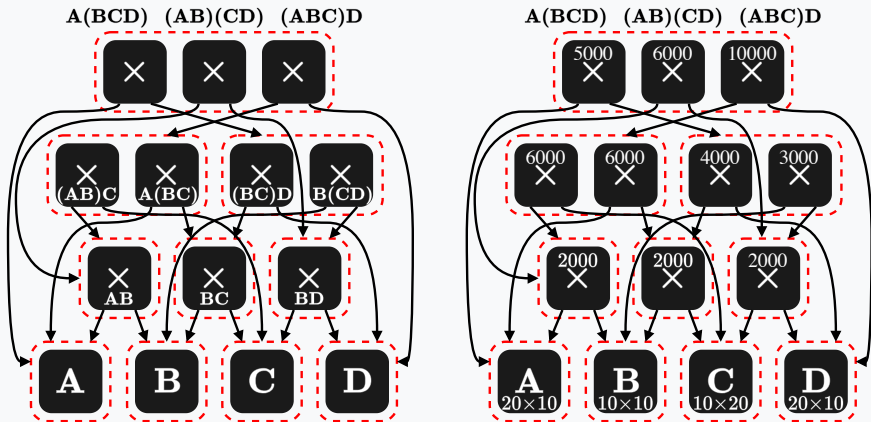
### 3. Extract the Optimal Expression



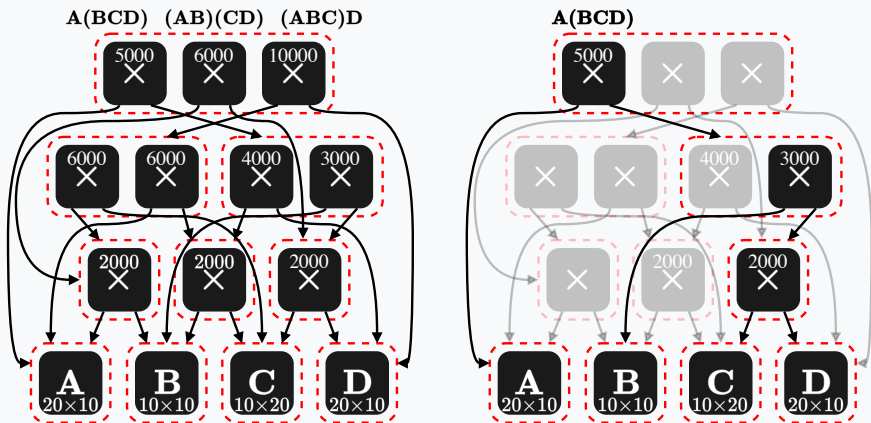
- Root e-class contains equivalent expressions of the program.
- Compute cost of e-nodes in the root e-class.
- Pick the e-node in the root e-class with the lowest cost.

### 3. Extract the Optimal Expression

$$\text{cost } \mathbf{XY} = \text{nrows}(\mathbf{X}) \cdot \text{ncols}(\mathbf{X}) \cdot \text{ncols}(\mathbf{Y})$$



# The Optimal Expression is A (B (CD))



# Polynomial Evaluation: Horner's Method

Reduce from  $O(n^2)$  to  $O(n)$  multiplications [2].

$$\begin{aligned} P(x) &= a_0 + a_1x + a_2x^2 + \cdots + a_{n-1}x^{n-1} + a_nx^n \\ &= a_0 + x(a_1 + x(a_2 + \cdots + x(a_{n-1} + xa_n))) \end{aligned}$$

What rewrites do we need to perform Horner's method?

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What rewrites do we need to perform Horner's method?

- Exponentiation:  $x^0 \Rightarrow 1$  and  $x^n \Rightarrow x \cdot x^{n-1}$
- Commutativity:  $x + y \Leftrightarrow y + x$  and  $xy \Leftrightarrow yx$
- Associativity:  $(x + y) + z \Leftrightarrow x + (y + z)$  and  $(xy)z \Leftrightarrow x(yz)$
- Distributivity:  $x(y + z) \Leftrightarrow xy + x \cdot z$
- Identity:  $x \cdot 1 \Rightarrow x$

# Outline

Compiler Optimization

Equality Saturation

Case Studies

**Applications**

# The egg Library

- **egg** is an efficient EqSat implementation in Rust [1].
- Fast: union-find with path compression & union by rank ( $\approx O(1)$  amortized)
- Flexible: pluggable cost functions and analysis
- Used in majority of EqSat research papers

# Applications of Equality Saturation & E-Graphs

**Compiler Optimization:** Herbie (floating-point accuracy), RISE (loop optimizations), RTL synthesis

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**Other Domains:** Query optimization, Julia IR optimization

*Key insight:* Wherever we have rewrite systems and need to find optimal solutions, e-graphs help explore the search space effectively.

# Limitations of Equality Saturation

Despite its power, equality saturation has important limitations:

- **Search space explosion:** E-graphs can grow exponentially with complex rewrite rules and large programs.
- **Scalability challenges:** Memory usage and time to saturation can be prohibitive for large programs. Moreover, extraction is NP-hard in general.
- **Cost model design:** Finding the right cost model for extraction is domain-specific and non-trivial.
- **Termination guarantees:** Not all rewrite systems will terminate or saturate in reasonable time.

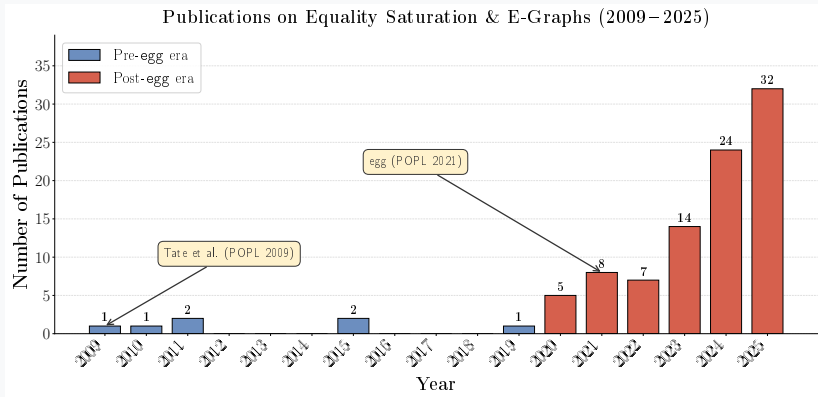
*Active research:* Guided saturation, pruning strategies, and heuristics aim to address these challenges.

# Scalability Study [2]

Bench.	#Rules	#Ops	Saturation	Canonicalization
Img Conv	1	29	<0.1ms	0.2ms
Vec Norm	1	44	<0.1ms	0.2ms
Poly	8	26	2ms	0.2ms
3MM	5	8	1ms	0.1ms
10MM	5	22	4ms	0.1ms
20MM	5	42	23ms	0.2ms
40MM	5	82	235ms	0.3ms
80MM	5	162	3732ms	0.6ms

# Research Trends: Growing Field

EqSat research growth since the original 2009 paper [1].



# Equality Saturation in the CASL Lab



**PI Christophe Dubach**



**Jonathan Van der Cruysse**

Latent idiom recognition using EqSat & Foresight



**Tzung-Han Juang**

EqSat for hardware resource sharing



**Adam Musa**

Driving EqSat with RL



**Aziz Zayed (me)**

EqSat and egraphs in modern compilers like MLIR

# Research Opportunities as an Undergrad

- COMP 400 research project
- Summer internship in the CASL lab
- NSERC USRA (~\$8000) — check if deadline has passed

# References

- [1] R. Tate, M. Stepp, Z. Tatlock, and S. Lerner, “Equality saturation: A new approach to optimization,” in *Proceedings of the 36th Annual ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages*, ser. POPL '09, Savannah, GA, USA: Association for Computing Machinery, 2009, pp. 264–276. DOI: 10.1145/1480881.1480915. [Online]. Available: <https://doi.org/10.1145/1480881.1480915>.
- [2] A.-E.-A. Zayed and C. Dubach, “Dialegg: Dialect-agnostic mlir optimizer using equality saturation with egglog,” in *Proceedings of the 23rd ACM/IEEE International Symposium on Code Generation and Optimization*, ser. CGO '25, Las Vegas, NV, USA: Association for Computing Machinery, 2025, pp. 271–283. DOI: 10.1145/3696443.3708957. [Online]. Available: <https://doi.org/10.1145/3696443.3708957>.