

Duality in Probabilistic Automata

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- 2 Deterministic Automata
- 3 Nondeterministic automata
- 4 Probabilistic Systems
- 5 Categorical Considerations
- 6 Conclusions

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- We have discovered an - apparently - new kind of duality for automata.
- Special case of this construction known since 1962 to Brzozowski.
- Works for probabilistic automata.
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Joint work with Doina Precup, Joelle Pineau at the RL Lab at McGill and Chris Hundt now working for Google. More recently with Nick Bezhanishvili and Clemens Kupke.

Deterministic Automata

- $\mathcal{M} = (S, \mathcal{A}, \mathcal{O}, \delta, \gamma)$: a deterministic finite automaton. S is the set of **states**, \mathcal{A} an **input alphabet** (actions), \mathcal{O} is a set of **observations**.
- $\delta : S \times \mathcal{A} \rightarrow S$ is the **state transition function**.
- $\gamma : S \rightarrow \mathbf{2}^{\mathcal{O}}$ or $\gamma : S \times \mathcal{O} \rightarrow \mathbf{2}$ is a labeling function.
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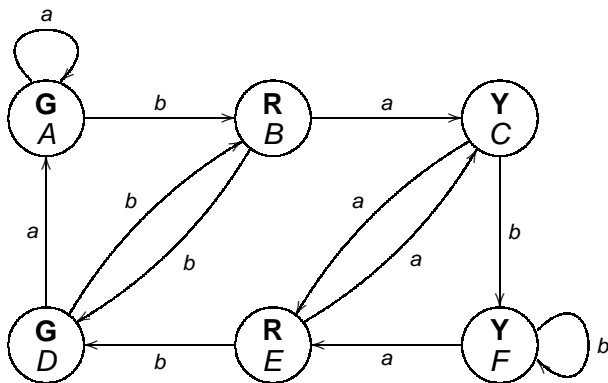
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An Example



States are $\{A, B, C, D, E, F\}$ and $\{G, R, Y\}$ are lights.

Testing the Machine

- What can we do with this machine?
- We can ask if *in the present state* the red light is on.
- We can ask whether *after an a-transition* the yellow light is on.
- We can ask whether *after some fixed sequence of transitions* a particular light is on.

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States Satisfy Tests (Or Not)

- R is satisfied by states $\{B, E\}$
- After a , **red** is on, is satisfied by $\{C, F\}$.
- After ba , **yellow** is on is satisfied by $\{A, D\}$

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A Simple Modal Logic

- Thinking of the elements of \mathcal{O} as formulas we can use them to define a simple modal logic. We define a *formula* φ according to the following grammar:

$$\varphi ::= \omega \in \mathcal{O} \mid (\mathbf{a})\varphi$$

where $\mathbf{a} \in \mathcal{A}$.

- We say $s \models \omega$, if $\omega \in \gamma(s)$ (or $\gamma(s, \omega) = T$).
We say $s \models (\mathbf{a})\varphi$ if $\delta(s, \mathbf{a}) \models \varphi$.
- Now we define $\llbracket \varphi \rrbracket_{\mathcal{M}} = \{s \in S \mid s \models \varphi\}$.

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An Equivalence Relation on Formulas

- We write sa as shorthand for $\delta(s, a)$.
- Define $\sim_{\mathcal{M}}$ between *formulas* as $\varphi \sim_{\mathcal{M}} \psi$ if $\llbracket \varphi \rrbracket_{\mathcal{M}} = \llbracket \psi \rrbracket_{\mathcal{M}}$.
- Note that this allows us to identify an equivalence class for φ with the set of states $\llbracket \varphi \rrbracket_{\mathcal{M}}$ that satisfy φ .
- Note that another way of defining this equivalence relations is

$$\varphi \sim_{\mathcal{M}} \varphi' := \forall s \in S. s \models \varphi \iff s \models \varphi'.$$

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- We also define an equivalence \equiv between *states* in \mathcal{M} as $s_1 \equiv s_2$ if for all formulas φ on \mathcal{M} , $s_1 \models \varphi \iff s_2 \models \varphi$.
- The equivalence relations \sim and \equiv are clearly closely related: they are the hinge of the duality between states and observations.
- We say that \mathcal{M} is *reduced* if the \equiv -equivalence classes are singletons.
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A Dual Automaton

- Given a finite automaton $\mathcal{M} = (\mathcal{S}, \mathcal{A}, \mathcal{O}, \delta, \gamma)$.
Let T be the set of $\sim_{\mathcal{M}}$ -equivalence classes of formulas on \mathcal{M} .
- We define $\mathcal{M}' = (\mathcal{S}', \mathcal{A}, \mathcal{O}', \delta', \gamma')$ as follows:
- $\mathcal{S}' = T = \{[\varphi]_{\mathcal{M}}\}$
- $\mathcal{O}' = \mathcal{S}$
- $\delta'([\varphi]_{\mathcal{M}}, a) = [(a)\varphi]_{\mathcal{M}}$
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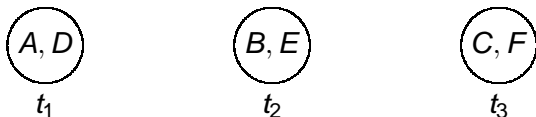
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The intuition

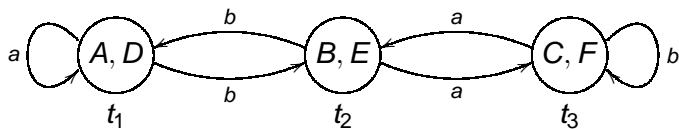
We have interchanged the states and the observations or propositions; more precisely we have interchanged equivalence classes of formulas - based on the observations - with the states. We have made the states of the old machine the observations of the dual machine.

The States of the Dual: Our Example



The states are equivalence classes of formulas but we have labelled them with the *set of states of the original machine* that satisfies the tests.

The Dual Machine in Full: Our Example



The Double Dual

- Now consider $\mathcal{M}'' = (\mathcal{M}')'$, the dual of the dual.
- Its states are equivalence classes of \mathcal{M}' -formulas.
- Each such class is identified with a set $[\![\varphi']\!]_{\mathcal{M}'}$ of \mathcal{M}' -states by which formulas in that class are satisfied, and
- each \mathcal{M}' -state is an equivalence class of \mathcal{M} -formulas.
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The Double Dual 2

- Let \mathcal{M}'' be the double dual, and for any state $s \in S$ in the original automaton we define

$$\text{Sat}(s) = \{[\varphi]_{\mathcal{M}} : s \models \varphi\}.$$

- Lemma: For any $s \in S$, $\text{Sat}(s)$ is a state in \mathcal{M}'' .
- In fact *all* the states of the double dual have this form.
- Lemma: Let $s'' = [\varphi]_{\mathcal{M}'} \in S''$ be any state in \mathcal{M}'' . Then $s'' = \text{Sat}(s_\varphi)$ for some state $s_\varphi \in S$.
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Minimality Properties

- If \mathcal{A} is reduced then Sat is a bijection from S to S'' .
- The statement above can be strengthened to show that we actually have an isomorphism of automata.
- If we define a notion of bisimulation we can show that a machine and its double dual are bisimilar.
- The minimality is, of course, due to the use of the equivalence relations in the duality.

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The Nondeterministic Case

- Here we consider automata of the type

$$\mathcal{M} = (\mathcal{S}, \mathcal{A}, \mathcal{O}, \delta : \mathcal{S} \times \mathcal{A} \rightarrow 2^{\mathcal{S}}, \gamma : \mathcal{S} \rightarrow 2^{\mathcal{O}}).$$

- We use the same formulas but we have a different notion of satisfaction: $Q \subseteq \mathcal{S}$

$$Q \models \omega \iff \exists s \in Q : \omega \in \gamma(s)$$

$$Q \models (a)\varphi \iff \delta(Q, a) \models \varphi.$$

- We define an appropriate notion of simulation and prove: \mathcal{M} is simulated by \mathcal{M}'' .
- The double dual is always deterministic; we have sneaked in the notion of determinization into the satisfaction relation.

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The Nondeterministic Case

- Here we consider automata of the type

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Brzozowski's Algorithm 1962

- Take a NFA and just reverse all the transitions and interchange initial and final states.
- Determinize the result.
- Reverse all the transitions again and interchange initial and final states.
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- This gives the minimal DFA recognizing the same language. The intermediate step can blow up the size of the automaton exponentially before minimizing it.

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Probabilistic systems

- Everything is discrete.
- Markov Decision Processes aka Labelled Markov Processes:

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Partial Observations

- Partially Observable Markov Decision Processes (POMDPs). We cannot see the entire state but we can see something.
- In process algebra we typically take actions as not always being enabled and we *observe whether actions are accepted or rejected*.
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Automata with State-based Observations

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- We use the same logic as before except that we give a probabilistic semantics and call the formulas “tests.” I write $a.t$ or at rather than $(a)\varphi$.
- Tests define functions from states to $[0, 1]$. If they define the same function they are equivalent.
- The explicit definition of these functions are:

$$\llbracket o \rrbracket_{\mathcal{E}}(s) = \gamma(s, o)$$

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Duality with e-tests

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- $\mathcal{O}' = S$
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- This machine has deterministic transitions and γ' is just the transpose of γ .

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The Double Dual

- If \mathcal{E} is the primal and \mathcal{E}' is the dual then the states of the double dual, \mathcal{E}'' are \mathcal{E}' -equivalence classes of tests.
- An “atomic” test is just an observation of \mathcal{E}' , which is just a state of \mathcal{E} so it has the form $\llbracket s \rrbracket_{\mathcal{E}'}$ for some s .
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More General Tests

- Recall the definition of a POMDP

$$\mathcal{M} = (\mathcal{S}, \mathcal{A}, \mathcal{O}, \delta_a : \mathcal{S} \times \mathcal{S} \rightarrow [0, 1], \gamma_a : \mathcal{S} \times \mathcal{O} \rightarrow [0, 1]).$$

- A **test** t is a non-empty sequence of actions followed by an observation, i.e. $t = a_1 \cdots a_n o$, with $n \geq 1$.
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Some Notation

- We need to generalize the transition function to keep track of the final state.

$$\begin{aligned}\delta_\epsilon(\mathbf{s}, \mathbf{s}') &= \mathbf{1}_{\mathbf{s}=\mathbf{s}'} & \forall \mathbf{s}, \mathbf{s}' \in \mathcal{S} \\ \delta_{a\alpha}(\mathbf{s}, \mathbf{s}') &= \sum_{\mathbf{s}''} \delta_a(\mathbf{s}, \mathbf{s}'') \delta_\alpha(\mathbf{s}'', \mathbf{s}') & \forall \mathbf{s}, \mathbf{s}' \in \mathcal{S}.\end{aligned}$$

- We have written $\mathbf{1}_{\mathbf{s}=\mathbf{s}'}$ for the indicator function.
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Equivalence on Experiments

- For experiments e_1, e_2 , we say

$$e_1 \sim_{\mathcal{M}} e_2 \Leftrightarrow \langle s | e_1 \rangle = \langle s | e_2 \rangle \forall s \in \mathcal{S}.$$

- Then $[e]_{\mathcal{M}}$ is the $\sim_{\mathcal{M}}$ -equivalence class of e .
- The construction of the dual proceeds as before by making equivalence classes of experiments the states of the dual machine and
- the states of the primal machine become the observations of the dual machine.

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$$(\mathcal{S}', \mathcal{A}, \mathcal{O}', \delta' : \mathcal{S}' \times \mathcal{A} \rightarrow \mathcal{S}', \gamma' : \mathcal{S}' \times \mathcal{O}' \rightarrow [0, 1]),$$

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The Main Theorem

- One has to check that everything is well defined.
- The main result is: The probability of a state s in the primal satisfying a experiment e , i.e. $\langle s|e \rangle$ is given by $\langle [s]_{\mathcal{M}'} |[e]_{\mathcal{M}} \rangle = \gamma''([s]_{\mathcal{M}'} |[e]_{\mathcal{M}})$, where $[s]$ indicates the equivalence class of the e -test on the dual which has s as an observation and an empty sequence of actions.

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AI Motivation

- One can plan when one has the model: value iteration etc., but quite often one does not have the model.
- In the absence of a model, one is forced to learn from data.
- Learning is hopeless when one has no idea what the state space is.
- There should be no such thing as absolute state! State is just a summary of past observations that can be used to make predictions.
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Automata as Coalgebras

Our automata are coalgebras of the following functor:

$$F(S) = S^A \times \mathbf{2}^{\mathcal{O}}, \quad F(f : S \rightarrow S') = \lambda(\alpha : \mathcal{A} \rightarrow S, O \subset \mathcal{O}).(f \circ \alpha, O).$$

The category of these coalgebras is called **PODFA**.

Homomorphisms

A homomorphism for these coalgebras is a function $f : S \rightarrow S'$ such that the following diagram commutes:

$$\begin{array}{ccc}
 S & \xrightarrow{f} & S' \\
 (\delta, \gamma) \downarrow & & \downarrow (\delta', \gamma') \\
 S^{\mathcal{A}} \times \mathbf{2}^{\mathcal{O}} & \xrightarrow{f^{\mathcal{A}} \times \text{id}} & S'^{\mathcal{A}} \times \mathbf{2}^{\mathcal{O}}
 \end{array}$$

where $f^{\mathcal{A}}(\alpha) = f \circ \alpha$.

This translates to the following conditions:

$$\forall s \in \mathbf{S}, \omega \in \mathcal{O}, \omega \in \gamma(s) \iff \omega \in \gamma'(f(s)) \quad (1)$$

and

$$\forall s \in \mathbf{S}, a \in \mathcal{A}, f(\delta(s), a) = \delta'(f(s), a). \quad (2)$$

The Dual Category

- The category of **finite boolean algebras with operators (FBAO)** has as objects finite boolean algebras B with
- the usual operations \wedge , \neg and constants \top and \perp and, in addition,
- together with unary operators (a) and constants $\underline{\omega}$.
- We denote an object by
$$\mathcal{B} = (B, \{(a) | a \in \mathcal{A}\}, \{\underline{\omega} | \omega \in \mathcal{O}\}, \top, \wedge, \neg).$$

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Morphisms

The morphisms are the usual boolean homomorphisms preserving, in addition, the constants and the unary operators. The following three equations hold:

$$(a)(b_1 \wedge b_2) = (a)b_1 \wedge (a)b_2, \quad (3a)$$

$$(a)\top = \top, \quad (3b)$$

$$\neg(a)\neg b = (a)b. \quad (3c)$$

Duality Theorem

There is a dual equivalence of categories

$$\mathbf{PODFA}^{op} \cong \mathbf{FBAO}.$$

One functor \mathcal{P} is just the contravariant power set functor and the other one \mathcal{H} maps a boolean algebra to its set of atoms.

Minimization?

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- So how do we explain the minimization?

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Definable Subsets

Define a logic \mathcal{L} by

$$\phi ::= \top \mid \perp \mid \phi_1 \wedge \phi_2 \mid \neg \phi \mid (\mathbf{a})\phi \mid \underline{\omega}$$

and define the **definable subsets** $\mathcal{D}(\mathcal{S})$ of a machine $\mathcal{M} = (\mathcal{S}, \delta, \gamma)$ as sets of the form $\llbracket \phi \rrbracket$.

- $\mathcal{D}(S)$ is a subobject of $\mathcal{P}(\mathcal{M})$
- in fact it is the *smallest* possible subalgebra and
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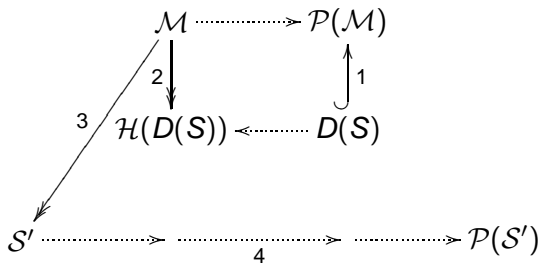
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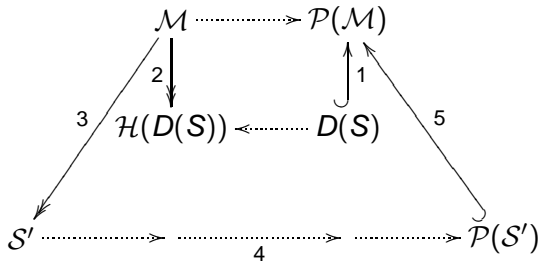
In Pictures

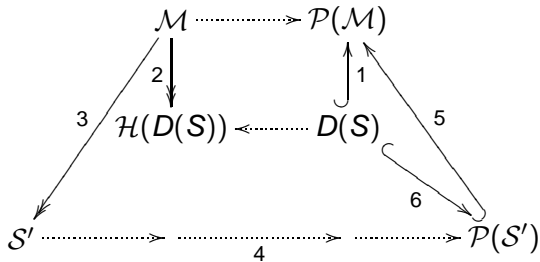
$$\mathcal{M} \dashrightarrow \mathcal{P}(\mathcal{M})$$

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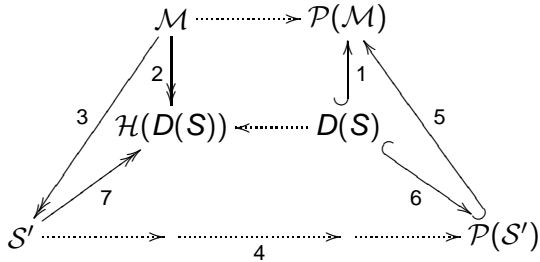
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The Secret of Minimization



A Simpler Logic

- Why did the minimization work with just the logic

$$\phi ::= \underline{\omega} | (\mathbf{a})\phi?$$

- With this logic the definable subsets $E(S)$ do not form a boolean algebra
- it is just a “set with operations”
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- Thus for **deterministic** automata the boolean algebra generated by $E(S)$ is just the same as $D(S)$ so the minimization picture works with boolean algebra generated by $E(S)$.
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- We are experimenting with these ideas for use in *approximation* in the RL Lab at McGill; joint with Doina Precup and Joelle Pineau and their students.
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- It is possible to eliminate state completely in favour of histories; when can this representation be compressed and made tractable?
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