

FOPPS Lectures: Probabilistic Bisimulation Metrics and Their Applications to Representation Learning

Lecture 2: Bisimulation metrics

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- 3 A logical view

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- 4 MDPs and reinforcement learning

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Many others more recently.

Process equivalence is fundamental

- Markov chains:

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- Markov decision processes: Bisimulation
- Labelled Concurrent Markov Chains with τ transitions: Weak Bisimulation

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- In the context of probability is exact equivalence reasonable?
- We say “no”. A small change in the probability distributions may result in bisimilar processes no longer being bisimilar though they may be very “close” in behaviour.
- Instead one should have a (pseudo)metric for probabilistic processes.

- Function $d : X \times X \rightarrow \mathbb{R}^{\geq 0}$

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- If we insist on $d(x, y) = 0$ iff $x = y$ we get a *metric*.
- A pseudometric defines an equivalence relation: $x \sim y$ if $d(x, y) = 0$.
- Define d^\sim on X / \sim by $d^\sim([x], [y]) = d(x, y)$; well-defined by triangle. This is a proper metric.

- Let R be an equivalence relation. R is a bisimulation if: $s R t$ if $(\forall a)$:

$$(s \xrightarrow{a} P) \Rightarrow [t \xrightarrow{a} Q, P =_R Q]$$

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- $=_R$ means that the measures P, Q agree on unions of R -equivalence classes.
- s, t are bisimilar if there is a bisimulation relating them.
- There is a maximum bisimulation relation.

Properties of bisimulation

- Establishing equality of states: Coinduction. Establish a bisimulation R that relates states s, t .

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- Establishing equality of states: Coinduction. Establish a bisimulation R that relates states s, t .
- Distinguishing states: Simple logic is complete for bisimulation.

$$\phi ::= \text{true} \mid \phi_1 \wedge \phi_2 \mid \langle a \rangle_q \phi$$

A metric-based approximate viewpoint

- Move from equality between processes to distances between processes (Jou and Smolka 1990).

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- Quantitative measurement of the distinction between processes.

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- Distinguishing states: Real-valued modal logics
- Equational and logical views coincide: Metrics yield same distances as real-valued modal logics
- Compositional reasoning by *non-expansiveness*.
Process-combinators take nearby processes to nearby processes.

$$\frac{d(s_1, t_1) < \epsilon_1, \quad d(s_2, t_2) < \epsilon_2}{d(s_1 \parallel s_2, t_1 \parallel t_2) < \epsilon_1 + \epsilon_2}$$

Summary of results

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- Distinguishing states: Real-valued modal logics
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- Results work for Markov chains, Labelled Markov processes, Markov decision processes and Labelled Concurrent Markov chains with τ -transitions.

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- Stability of distance under temporal evolution: “Nearby states stay close *forever*.”
- Metrics should be computable.

Bisimulation Recalled

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where $P =_R Q$ if

$$(\forall R\text{-closed } E) P(E) = Q(E)$$

A putative definition of a metric-bisimulation

- m is a metric-bisimulation if: $m(s, t) < \epsilon \Rightarrow$:

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- Problem: what is $m(P, Q)$? — Type mismatch!!
- Need a way to lift distances from states to a distances on distributions of states.

A detour: Kantorovich metric

- Metrics on probability measures on metric spaces.

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- Arises in the solution of an LP problem: *transshipment*.

An LP version for Finite-State Spaces

When state space is finite: Let P, Q be probability distributions. Then:

$$m(P, Q) = \max \sum_i (P(s_i) - Q(s_i))a_i$$

subject to:

$$\begin{aligned} \forall i. 0 \leq a_i \leq 1 \\ \forall i, j. a_i - a_j \leq m(s_i, s_j). \end{aligned}$$

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$$\min \sum_{i,j} l_{ij} m(s_i, s_j) + \sum_i x_i + \sum_j y_j$$

subject to:

$$\forall i. \sum_j l_{ij} + x_i = P(s_i)$$

$$\forall j. \sum_i l_{ij} + y_j = Q(s_j)$$

$$\forall i, j. l_{ij}, x_i, y_j \geq 0.$$

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- We prove many equations by using the primal form to show one direction and the dual to show the other.

Example 1

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- In dual, match each state with itself, $l_{ij} = \delta_{ij}P(s_i), x_i = y_j = 0$. So:

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- This clearly cannot be lowered further so this is the min.

Example 2

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- Lower bound from primal: Choose $a_s = 0, a_t = r$, all others to match the constraints. Then

$$\sum_i (\delta_t(s_i) - \delta_s(s_i)) a_i = r.$$

The Importance of Example 2

We can *isometrically* embed the original space in the metric space of distributions.

Example 3 - I

- Let $P(s) = r, P(t) = 0$ if $s \neq t$. Let $Q(s) = r', Q(t) = 0$ if $s \neq t$.

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- Then $m(P, Q) = |r - r'|$.
- Assume that $r \geq r'$.

Lower bound from primal: yielded by $\forall i. a_i = 1$,

$$\sum_i (P(s_i) - Q(s_i)) a_i = P(s) - Q(s) = r - r'.$$

Example 3 - II

Upper bound from dual: $l_{ss} = r'$ and $x_s = r - r'$, all others 0

$$\sum_{i,j} l_{ij} m(s_i, s_j) + \sum_i x_i + \sum_j y_j = x_s = r - r'.$$

and the constraints are satisfied:

$$\sum_j l_{sj} + x_s = l_{ss} + x_s = r$$

$$\sum_i l_{is} + y_s = l_{ss} = r'.$$

Summary

Given a metric on states in a metric space, can lift to a metric on probability distributions on states.

Metric “bisimulation”

- m is a metric-bisimulation if: $m(s, t) < \epsilon \Rightarrow$:

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- Thm: *Canonical least metric exists.*

Tarski's theorem

If L is a complete lattice and $F : L \rightarrow L$ is monotone then the set of fixed points of F with the induced order is itself a complete lattice. In particular there is a least fixed point and a greatest fixed point.

Metrics: some details

- \mathcal{M} : 1-bounded pseudometrics on states with ordering

$$m_1 \preceq m_2 \text{ if } (\forall s, t) [m_1(s, t) \geq m_2(s, t)]$$

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$$\begin{aligned} \perp(s, t) &= \begin{cases} 0 & \text{if } s = t \\ 1 & \text{otherwise} \end{cases} \\ \top(s, t) &= 0, (\forall s, t) \\ (\sqcap \{m_i\})(s, t) &= \sup_i m_i(s, t) \end{aligned}$$

Greatest fixed-point definition

- Let $m \in \mathcal{M}$. $F(m)(s, t) < \epsilon$ if:

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- F is monotone on \mathcal{M} , and metric-bisimulation is the greatest fixed point of F .
- The closure ordinal of F is ω .

Splitting Lemma (Jones)

Let P and Q be probability distributions on a set of states. Let P_1 and P_2 be such that: $P = P_1 + P_2$. Then, there exist Q_1, Q_2 , such that $Q_1 + Q_2 = Q$ and

$$m(P, Q) = m(P_1, Q_1) + m(P_2, Q_2).$$

The proof uses the duality theory of LP for discrete spaces and Kantorovich-Rubinstein duality for continuous spaces.

Definition

Given two probability measures P_1, P_2 on (X, Σ) , a *coupling* is a measure Q on the product space $X \times X$ such that the marginals are P_1, P_2 . Write $\mathcal{C}(P_1, P_2)$ for the set of couplings between P_1, P_2 .

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Theorem

Let (X, d) be a compact metric space. Let P_1, P_2 be Borel probability measures on X

$$\sup_{f: X \rightarrow [0,1] \text{ nonexpansive}} \left\{ \int_X f dP_1 - \int_X f dP_2 \right\} = \inf_{Q \in \mathcal{C}(P_1, P_2)} \left\{ \int_{X \times X} d \, dQ \right\}$$

- Develop a real-valued “modal logic” based on the analogy:

Real-valued modal logic I

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Kozen’s analogy

Program Logic	Probabilistic Logic
State s	Distribution μ
Formula ϕ	Random Variable f
Satisfaction $s \models \phi$	$\int f d\mu$

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Kozen’s analogy

Program Logic	Probabilistic Logic
State s	Distribution μ
Formula ϕ	Random Variable f
Satisfaction $s \models \phi$	$\int f d\mu$

- Define a metric based on how closely the random variables agree.



$$f ::= \mathbf{1} \mid \max(f, f) \mid h \circ f \mid \langle a \rangle f$$

Real-valued modal logic II

- $$f ::= \mathbf{1} \mid \max(f, f) \mid h \circ f \mid \langle a \rangle . f$$

- | | | | |
|----------------------------|-----|---|-----------------|
| $\mathbf{1}(s)$ | $=$ | 1 | True |
| $\max(f_1, f_2)(s)$ | $=$ | $\max(f_1(s), f_2(s))$ | Conjunction |
| $h \circ f(s)$ | $=$ | $h(f(s))$ | Lipschitz |
| $\langle a \rangle . f(s)$ | $=$ | $\gamma \int_{s' \in \mathcal{S}} f(s') \tau_a(s, ds')$ | a -transition |

where h 1-Lipschitz : $[0, 1] \rightarrow [0, 1]$ and $\gamma \in (0, 1]$.

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- $d(s, t) = \sup_f |f(s) - f(t)|$
- Thm: d coincides with the fixed-point definition of the bisimulation metric.

Finitary syntax for the modal logic

$\mathbf{1}(s)$	$=$	1	True
$\max(f_1, f_2)(s)$	$=$	$\max(f_1(s), f_2(s))$	Conjunction
$(1 - f)(s)$	$=$	$1 - f(s)$	Negation
$\lfloor f_q(s) \rfloor$	$=$	$\begin{cases} q, & f(s) \geq q \\ f(s), & f(s) < q \end{cases}$	Cutoffs
$\langle a \rangle.f(s)$	$=$	$\gamma \int_{s' \in S} f(s') \tau_a(s, ds')$	a -transition

q is a rational.

Markov decision processes

$$(S, \mathcal{A}, \forall a \in \mathcal{A}, P^a : S \rightarrow \mathcal{D}(S), \mathcal{R} : \mathcal{A} \times S \rightarrow \mathbb{R})$$

where

S : the state space, we will take it to be a finite set.

\mathcal{A} : the actions, a finite set

P^a : the transition function; $\mathcal{D}(S)$ denotes distributions over S

\mathcal{R} : the reward, could readily make it stochastic.

Will write $P^a(s, C)$ for $P^a(s)(C)$.

MDP

$$(S, \mathcal{A}, \forall a \in \mathcal{A}, P^a : S \rightarrow \mathcal{D}(S), \mathcal{R} : \mathcal{A} \times S \rightarrow \mathbb{R})$$

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Policy

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The goal is **choose** the best policy: numerous algorithms to find or approximate the optimal policy.

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- These are the celebrated Bellman equations.

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- Bisimulation can be defined as the *greatest fixed point* of a relation transformer.

The bisimulation metric

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- We can find the bisimulation as the fixed point of T_K by iteration:
 d^\sim .

Ferns' theorem

Ferns et al. - 2004,2005

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- Pablo Castro has adapted bisimulation metrics to deal with specific policies.

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- How does one reason about these metrics in a way similar to equational reasoning?
- Valeria will tell you on Thursday morning!