

# Applications of computer science in the life sciences

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# What can computer science do for the life sciences?

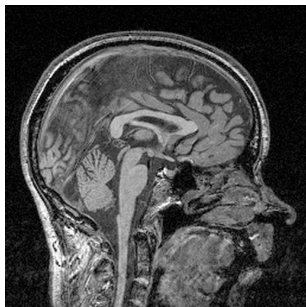
- ▶ Medical image analysis
- ▶ Genomics and phylogenetics
- ▶ Drug design and discovery
- ▶ Assistive robotics
- ▶ Brain-computer interfaces
- ▶ Simulation of biological systems
- ▶ Medical treatment optimization

# Relevant techniques from computer science

- ▶ Searching and sorting
- ▶ Network analysis
- ▶ Robotics and artificial intelligence
- ▶ Machine learning and pattern classification
- ▶ **Reinforcement learning**

# Medical image analysis

- ▶ The resolution and quality of medical images has exploded over the past two decades. Example applications from brain imaging are:



- ▶ **Automatic tissue classification**
- ▶ Image-guided neurosurgery
- ▶ Cortical thickness measurement
- ▶ **Decoding cognitive states**

# Automatic tissue classification

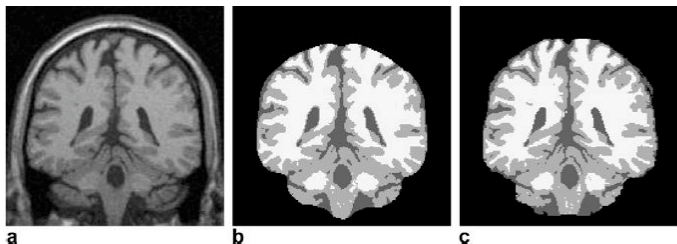


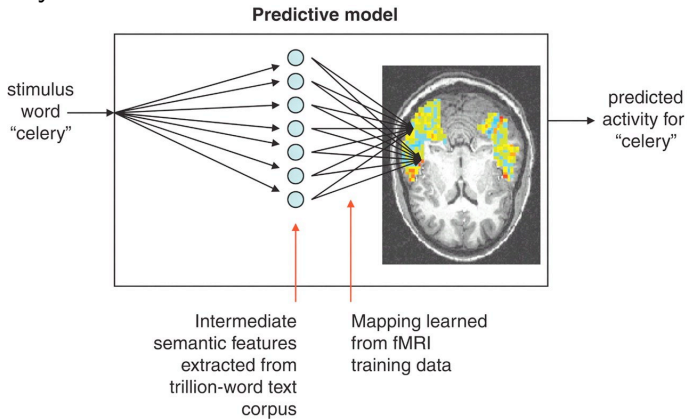
Fig. 1. Qualitative analysis of the proposed algorithm with BrainWeb data (Collins et al., 1998) with 5% noise and a 40% bias field: (a) a coronal slice of the data; (b) the classification produced by the proposed method and (c) the ground truth.

Awate et al. 2006

- ▶ Given a scalar intensity for each “voxel”.
- ▶ Calculate contributions of white matter, grey matter, and cerebrospinal fluid.
- ▶ Central idea: Use knowledge about other images to calculate the “most likely” interpretation of a new image

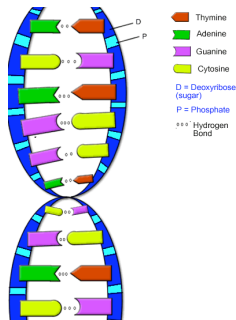
# Decoding cognitive states

A model trained from fMRI images of a test subject can identify the noun the subject was thinking of with over 70% accuracy.



# Genomics and phylogenetics

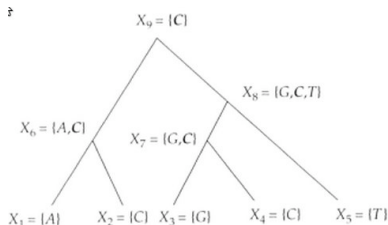
- ▶ Computer algorithms are increasingly critical to research in genomics and evolutionary relationships among organisms.
- ▶ Often lumped under “bioinformatics”



- ▶ Gene and protein sequencing
- ▶ Discovery of regulatory sites and relationships
- ▶ **Reconstruction of ancestral sequences**
- ▶ Analysis of regulatory networks

# Reconstruction of ancestral sequences

- ▶ First proposed in 1963 by Pauling and Zuckerkandl
- ▶ Begin with sequences of existing genes or proteins
- ▶ Assume constant rates of mutation (parsimony)
- ▶ Calculate most likely ancestral sequence
- ▶ Synthesize and evaluate ancestral sequence in laboratory

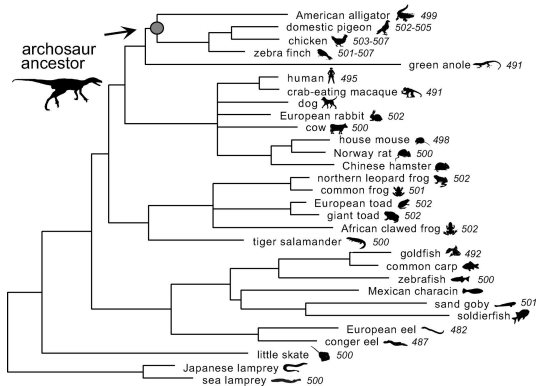


From Liberles (ed.) 2007



# Reconstruction of ancestral sequences

- ▶ Chang et al. (2002) synthesized archosaur visual pigments (rhodopsin)
- ▶ Suggested that the wavelength of maximum sensitivity was consistent with nocturnal behavior



# Drug design and discovery

- ▶ At least 500,000 proteins in the human proteome
- ▶ Roughly 2% are well studied (Young, 2009)
- ▶ Computational methods are applied to:
  - ▶ Virtual screening
  - ▶ Protein structure and folding

# Assistive robotics

- ▶ Uses robotics to aid patients with impaired mobility or cognition.



SmartWheeler

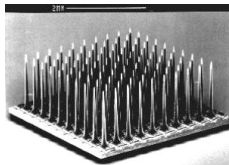
- ▶ Automatic obstacle avoidance
- ▶ Intelligent user interface
- ▶ Navigation and mapping

# Brain-computer interfaces

- ▶ “A direct brain-computer interface is a device that provides the brain with a new, non-muscular communication and control channel.” (Wolpaw et al. 2002)
- ▶ Electrical signals from surface or implanted electrodes can control assistive technologies
- ▶ Current research seeks methods to extract more information from signals
- ▶ Not all subjects perform equally well
- ▶ Of special interest in assistive robotics research

# Brain-computer interfaces

- ▶ Surface electrodes (EEG) are inherently low bandwidth
- ▶ USF P300 System
- ▶ Surgically implanted cortical electrodes can improve bandwidth:



University of Utah

- ▶ Machine learning algorithms improve decoding of EEG and cortical signals

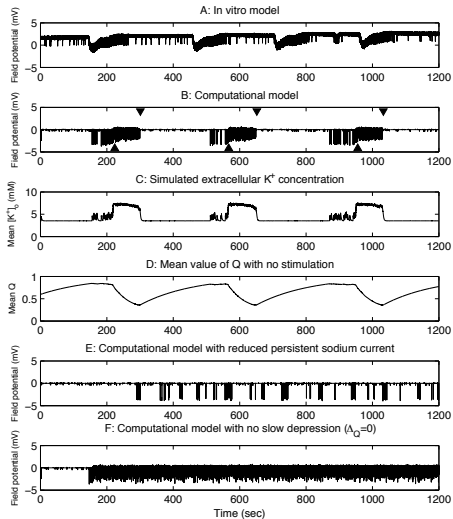
# Simulation of biological systems

- ▶ Computer models can provide simulated data for a wide range of biological phenomena:
  - ▶ Cellular growth and development
  - ▶ **Nervous system activity**
  - ▶ Motor control (eye, arm, etc.)
  - ▶ Population dynamics (predator-prey relationships, e.g.)
  - ▶ Disease transmission and progression
- ▶ Such models may be used to make novel predictions for further research or to evaluate potential therapies.

## Nervous system activity

- ▶ Builds on early quantitative models of the nervous system (e.g Hodgkin and Huxley, 1952)
- ▶ Relies on a simplified model of neurons and synapses
- ▶ Calculates timecourse of network behavior using numeric integration
- ▶ Can be used to predict effects of different connectivity patterns, drug effects, etc.
- ▶ Several major labs and publications emphasize these techniques

# Nervous system activity





# Medical treatment optimization

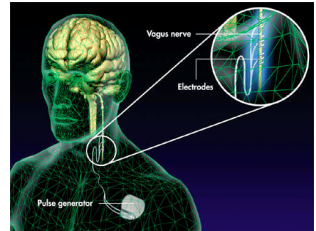
- ▶ Traditional approaches often rely on educated guesses
- ▶ Treatment and trials are simple and relatively static
- ▶ New emphasis on *adaptive treatment design* or *dynamic treatment regimes*.
- ▶ *Reinforcement learning* has been applied to optimize:
  - ▶ Antiretroviral drug treatments for HIV (Ernst et al. 2005)
  - ▶ Treatment for chronic depression (Pineau et al. 2007)
  - ▶ Lung cancer treatment (Zhao et al. 2009)
  - ▶ **Electrical stimulation for epilepsy** (Guez et al. 2008)
- ▶ These new methods suggest changes in clinical trial methodology (Collins et al. 2005)

# About epilepsy

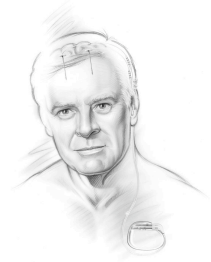
- ▶ A disorder characterized by abnormal periods of electrical activity in the brain, called seizures
  - ▶ Affects ~1% of the population
  - ▶ Multiple causes - genetics, injury, tumors
  - ▶ Range of severities
  - ▶ Drugs have 60-70% success rate
  - ▶ Surgery required in extreme cases

# Electrical stimulation for epilepsy treatment

- ▶ FDA-approved devices stimulate the vagus nerve
- ▶ Pending devices use deep brain stimulation
- ▶ No certain explanation for efficacy
- ▶ Existing devices are *open loop*
- ▶ Also used to treat Parkinson's disease, depression, etc.

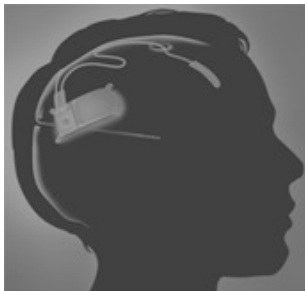


Cyberonics, Inc.



# Responsive stimulation devices

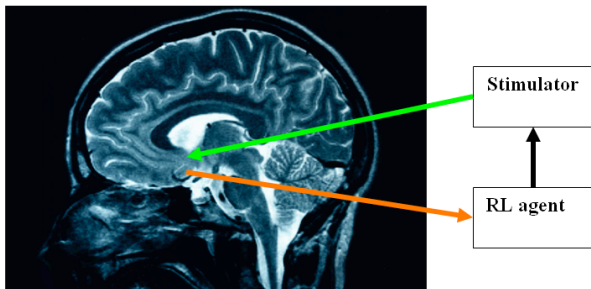
- ▶ “Responsive stimulation” (i.e. closed loop) devices are in preliminary trials
- ▶ At present, these implement a “detect and stimulate” policy
- ▶ Unclear whether *prediction* of seizures is possible



Neuropace, Inc.

# Goal of our research

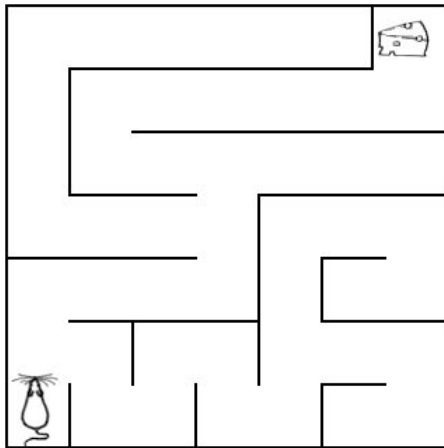
- ▶ An adaptive treatment algorithm using reinforcement learning
  - ▶ Improved efficacy
  - ▶ Reduced side effects
  - ▶ Increased battery life



# What is reinforcement learning?

Agents that “learn by doing”

Inspired by ideas from psychology:

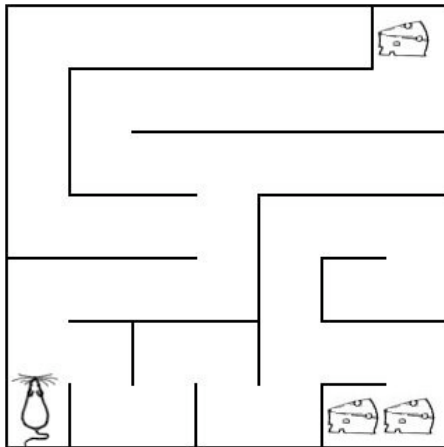


# What is reinforcement learning?

- ▶ Initially, the rat “explores” the environment, making many errors
- ▶ After many trials, the rat will move more quickly and accurately towards the goal, “exploiting” its knowledge

# What is reinforcement learning?

Exploration vs. exploitation:





# What is reinforcement learning?

- ▶ A “semi-supervised” machine learning method. An *agent* explores an *environment* consisting of:
  - ▶ A set of *states* describing the environment.
  - ▶ A set of *actions* that the agent may choose.
  - ▶ The next state depends only on the current state and action (the “Markov” assumption).
  - ▶ A *reward* or penalty is given for each action and state.
- ▶ The goal is to maximize the total discounted reward.
- ▶ The agent estimates the *value* of each state or state/action pair.
- ▶ The agent learns a *policy* which selects the best action for each state.

# The mathematics of RL

- ▶ We treat the problem as a *Markov Decision Process*:
  - ▶ Sets of states  $\mathcal{S}$  and actions  $\mathcal{A}$ .
  - ▶ A transition function which defines how states follow one another:  $P(s, a, s') = Pr(s_{t+1} = s' | s_t = s, a_t = a)$ .
  - ▶ A scalar reward function  $r_t = R(s, a)$ .
  - ▶ Some policy  $\pi$ , such that  $a_t = \pi(s_t)$ . The policy may be either deterministic or stochastic.
  - ▶ A discount factor,  $\gamma$ , which must be less than or equal to one. This causes the system to put a greater value on “immediate” rewards.
- ▶ The goal is to learn a policy to maximize the expected future rewards:  $V = \sum_{t=0}^T \gamma^t R(s_t, \pi(s_t))$ .

## Q-functions

- ▶ Many of the simple RL algorithms work by estimating something we call the “Q-function”:  $q = Q(s, a)$ .
- ▶ This is a scalar function which returns a value answering the question: “What is the value of taking action  $a$  in state  $s$ , under some assumed policy?”
- ▶ A deterministic policy can be derived from our Q-function:  $\pi(s) = \arg \max_{a \in \mathcal{A}} Q(s, a)$ .
- ▶ We can do this *without* knowing the state transition function or the reward function.

# How does RL work?

- ▶ The agent begins in some initial state  $s$
- ▶ For each time step:
  - ▶ The agent chooses an action  $a$ , based on its estimates of the values of possible future states,  $Q(s, a)$
  - ▶ The agent performs the action, and observes the new state  $s'$ , and receives a reward  $r$
  - ▶ The agent improves its estimate of the current value of each state and action using a “temporal difference” rule:

$$Q(s, a) = Q(s, a) + \alpha(r + \gamma \max_a Q(s', a) - Q(s, a)) \quad (1)$$

where  $\alpha$  is a learning rate.

# Successes of reinforcement learning

- ▶ Demonstrated ability to find good solutions in randomized or poorly-modeled problems:
  - ▶ Backgammon (Tesauro 1995)
  - ▶ Elevator scheduling (Crites and Barto 1996,1998)
  - ▶ Helicopter flight (Ng et al. 2004,2007)
  - ▶ Tetris (Farias and van Roy, 2006)
- ▶ Some serious challenges, however:
  - ▶ Tends to require lots of data for training
  - ▶ Hard to use in large or continuous state/action spaces

## Easy RL: Tic Tac Toe

	X		O	
—		—		—
	X			
—		—		—
	X		O	

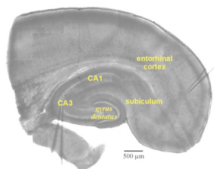
- ▶ A simple problem:
  - ▶ Finite: Countable states (board positions) and actions
  - ▶ Deterministic: Any legal action leads to a unique state
  - ▶ Simple actions: Limited set of legal moves
- ▶ Reward of +1 for a win, 0 for a loss (for example)
- ▶ As it visits states, an agent estimates the state's value using the temporal difference rule
- ▶ Agent must *exploit* knowledge and *explore* alternatives
- ▶ Given enough games, the agent is very likely to discover the best action for each state

# Difficult RL: Adaptive stimulation

- ▶ A *much* more difficult problem:
  - ▶ Infinite: Many continuous state variables, derived from recordings of electrical activity
  - ▶ Non-deterministic: State changes aren't perfectly predictable
  - ▶ Complex actions: e.g. continuous stimulation frequency
- ▶ Reward may be, for example, 0 if normal, -1 for stimulation, -100 for seizure
- ▶ Preliminary algorithms have shown some promise using *in vitro* data

# Current research

- ▶ RL algorithms trained *off line*
- ▶ We have begun testing the algorithms using *in vitro* experiments.



Hungarian Academy of Sciences

- ▶ Slices of rat brain tissue are treated with drugs that cause “seizure-like” activity, and we attach recording and stimulating electrodes.
- ▶ Preliminary results show that an RL agent can suppress seizures with less stimulation



## Other medical applications of RL

- ▶ Use RL to optimize other chronic treatment:
  - ▶ Drug therapy for mental illness
  - ▶ Radiation therapy for cancer
  - ▶ Structured treatment interruptions for HIV
  - ▶ Substance abuse
- ▶ Design drug trials to allow for RL optimization of treatment (Murphy, 2005).

# Conclusion

- ▶ Medical and biological research is now driving, and being driven by, developments in computer science.
- ▶ More and more data is being produced - the problem is often how to process it automatically.
- ▶ This requires something a bit deeper than off-the-shelf applications.
- ▶ Lots of opportunities for interdisciplinary collaboration.