

**Overview** Reduced-Rank Regression extension to the multilinear setting. Regression problem with tensor structured outputs. sun temp. Approximation algorithm rather than convex relaxation. Fast and efficient algorithm with strong theoretical guarantees. Tensors Higher-order generalization of vectors and matrices:  $\mathbf{M} \in \mathbb{R}^{d_1 imes d_2}$  : d1 Μ  $\mathcal{T} \in \mathbb{R}^{d_1 imes d_2 imes d_3}$  : **Tensors: Matricizations** •  $\mathcal{T} \in \mathbb{R}^{d_1 \times d_2 \times d_3}$  can be reshaped into a matrix as В Α  $\mathbf{T}_{(1)} \in \mathbb{R}^{d_1 imes d_2 d_3}$  $\mathsf{T}_{(2)} \in \mathbb{R}^{d_2 imes d_1 d_3}$  $\mathsf{T}_{(3)} \in \mathbb{R}^{d_3 imes d_1 d_2}$ **(**1) **Tensors: Multiplication with Matrices** Α Μ А  $\mathcal{T}$  $d_1$ Β m<sub>2</sub> Β  $\mathcal{T} imes_1 \mathbf{A} imes_2 \mathbf{B} imes_3 \mathbf{C} \in \mathbb{R}^{m_1 imes m_2 imes m_3}$  $\mathbf{AMB}^{ op} \in \mathbb{R}^{m_1 imes m_2}$ For vectors, we note  $\mathcal{T} \bullet_n \mathbf{v} = \mathcal{T} \times_n \mathbf{v}^\top$ **Tucker Decomposition and Multilinear Rank** Multilinear rank:  $\operatorname{rank}_{mi}(\mathcal{T}) = (R_1, R_2, R_3) \Leftrightarrow R_i = \operatorname{rank}(\mathbf{T}_{(i)}) \text{ for } i = 1, 2, 3$ Tucker decomposition:  $U_1$ auU<sub>2</sub>

 $\mathcal{T} = \mathcal{G} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \mathbf{U}_3$  with  $\mathbf{U}_i^{\top} \mathbf{U}_i = \mathbf{I}$  for all *i*. • Multilinear rank = smallest  $(R_1, R_2, R_3)$  such that (1) holds.

(1)

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Find 3 low-dimensional subspaces  $U_0, U_1, U_2$  such that projecting  $\mathcal{Y}$  onto the spaces  $\mathbf{X}U_0, U_1, U_2$  is close to  $\mathcal{Y}$ . NP-hard... Solve each arg min<sub>11</sub>  $\|\mathcal{Y} \times_{i+1} \Pi_i - \mathcal{Y}\|_F^2$  independently instead.

 $\rightarrow$  Without low-rank constraint:  $\mathcal{O}\left(\sqrt{d_0 d_1 \cdots d_p}\right)$ 

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## Higher-Order Low-Rank Regression

arg min  $\|\boldsymbol{\mathcal{W}} \times_1 \boldsymbol{X} - \boldsymbol{\mathcal{Y}}\|_F^2 + \gamma \|\boldsymbol{\mathcal{W}}\|_F^2$  s.t. rank<sub>m</sub>( $\boldsymbol{\mathcal{W}}$ )  $\leq (\boldsymbol{R}_0, \cdots, \boldsymbol{R}_p)$ 

# Algorithm (HOLRR).

Input:  $\mathbf{X} \in \mathbb{R}^{N \times d_0}$ ,  $\mathcal{Y} \in \mathbb{R}^{N \times d_1 \times \cdots \times d_p}$ , rank  $(R_0, R_1, \cdots, R_p)$ . 1:  $\mathbf{U}_0 \leftarrow top \ R_0 \ eigenvectors \ of (\mathbf{X}^\top \mathbf{X} + \gamma \mathbf{I})^{-1} \mathbf{X}^\top \mathbf{Y}_{(1)} \mathbf{Y}_{(1)}^\top \mathbf{X}$ 2: **for** *i* = 1 **to** *p* **do** *3:*  $\mathbf{U}_i \leftarrow top \ R_i \ eigenvectors \ of \ \mathbf{Y}_{(i+1)} \mathbf{Y}_{(i+1)}^{\top}$ *5:*  $\mathbf{M} \leftarrow \left(\mathbf{U}_{\mathbf{0}}^{\top}(\mathbf{X}^{\top}\mathbf{X} + \gamma\mathbf{I})\mathbf{U}_{\mathbf{0}}\right)^{-1}\mathbf{U}_{\mathbf{0}}^{\top}\mathbf{X}^{\top}$ 6:  $\mathcal{G} \leftarrow \mathcal{Y} \times_1 \mathbf{M} \times_2 \mathbf{U}_1^\top \times_3 \cdots \times_{p+1} \mathbf{U}_p^\top$ 7: return  $\mathcal{G} \times_1 \mathbf{U}_0 \times_2 \cdots \times_{D+1} \mathbf{U}_D$ 

## **Approximation Guarantees**

## ► HOLRR is a quasi-optimal algorithm.

Let  $\mathcal{W}^*$  be a solution of Problem 2, let  $\hat{\mathcal{W}}$  be the regression tensor returned by HOLRR, and let  $\mathcal{J}$  denote the loss function. Then,  $\mathcal{J}(\hat{\mathcal{W}}) \leq (p+1)\mathcal{J}(\mathcal{W}^*).$ 

### **Statistical Guarantees**

► HOLRR recovers the low-rank regression (LRR) solution.

• Training sample  $\{\mathbf{x}^{(n)}, \mathbf{y}^{(n)}\}_{n=1}^{N} \subset \mathbb{R}^{d_0} \times \mathbb{R}^{d_1}$ • Regularization parameters:  $1 \le R \le d_0$  and  $\gamma \ge 0$ •  $\mathbf{W}_{HOLRR} \in \mathbb{R}^{d_0 \times d_1}$ : HOLRR estimator with rank constraint  $(R_0, R_1) = (R, d_1)$  and ridge parameter  $\gamma$ •  $\mathbf{W}_{LRR} \in \mathbb{R}^{d_0 \times d_1}$ : LRR estimator with rank constraint R and ridge parameter  $\gamma$ 

Then,  $\mathbf{W}_{HOLRR} = \mathbf{W}_{LRR}$ .

► HOLRR is statistically consistent.

►  $\mathbf{x}^{(1)}, \cdots, \mathbf{x}^{(N)} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  i.i.d. in  $\mathbb{R}^{d_0}$  $\boldsymbol{k} \boldsymbol{\xi}^{(1)}, \cdots, \boldsymbol{\xi}^{(N)} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}) \text{ i.i.d. in } \mathbb{R}^{d_1 \times \cdots \times d_p}$ •  $\mathcal{W}^* \in \mathbb{R}^{d_0 \times \cdots \times d_p}$  a tensor s.t.  $\operatorname{rank}_{m'}(\mathcal{W}) = (R_0, \cdots, R_p)$  $\mathcal{Y}^{(n)} = \mathcal{W}^* \bullet_1 \mathbf{x}^{(n)} + \boldsymbol{\xi}^{(n)}$  for all  $n \in [N]$ .

• Let  $\mathcal{W}_N$  be the estimator returned by HOLRR with training sample  $\{(\mathbf{x}^{(n)}, \mathcal{Y}^{(n)})\}_{n=1}^{N}$ , rank parameter  $(R_0, \cdots, R_p)$  and regularization parameter  $\gamma = 0$ 

Then, for any  $\varepsilon > 0$  we have

$$\lim_{N\to\infty}\mathbb{P}[\|\boldsymbol{\mathcal{W}}^*-\boldsymbol{\mathcal{W}}_N\|_F>\varepsilon]=0$$

Generalization bound for the class of functions

$$\mathcal{F}_{ml} = \{ \mathbf{X} \mapsto \mathcal{W} \bullet_1 \mathbf{X} : \operatorname{rank}_{ml}(\mathcal{W}) = (R_0, \cdots, R_p) \}.$$

Let  $\mathcal{L} : \mathbb{R}^{d_1 \times \cdots \times d_p} \to \mathbb{R}$  be a loss function bounded by M. For all  $h \in \mathcal{F}_{ml}$ , for any  $\delta > 0$ , with probability at least  $1 - \delta$ :

 $R(h) \leq \hat{R}(h) + M \sqrt{\frac{2D\log\left(\frac{4e(p+2)d_0d_1\cdots d_p}{\max_{i\geq 0}d_i}\right)\log N}{N}} + M \sqrt{\frac{\log\left(\frac{1}{\delta}\right)}{2N}}$ where  $D = R_0 R_1 \cdots R_p + \sum_{i=0}^p R_i d_i$ .



- **HOPLS**: Higher-order partial least squares [5].

(left) Synthetic data. (right) Effect of over-estimating the rank.





# Real data: forecasting task

### Data set

CCDS Foursquar Meteo-UK

Table:

Data set

Synthetic CCDS Foursquare Meteo UK

## **Future Works**

## References



son of HOLRR with:

**RLS**: Regularized least squares.

**LRR**: Low-rank regression.

**ADMM**: Convex relaxation (trace norms) [2, 4].

MLMT-NC: Nonconvex multilinear multitask learning [4].

• Greedy: Greedy approach for spatio-temporal forecasting [1].

Matrix vs. tensor rank regularization.

CCDS: 17 variables across 125 locations from 1990 to 2001. Foursquare: check-in records by 121 users in 15 categories over 1200 time intervals.

Meteo-UK: 5 variables across 16 locations from 1960 to 2000.

	ADMM	Greedy	HOPLS		K-HOLRR				
				HULNN	(poly)	(rbf)			
	0.8448	0.8325	0.8147	0.8096	0.8275	0.7913			
re -	0.1407	0.1223	0.1224	0.1227	0.1223	0.1226			
<	0.6140	—	0.625	0.5971	0.6107	0.5886			
Average RMSE over 10 splits train/test data sets (90%/10%)									

MI MT-NC	ADMM	Greedy	HOPLS	HOLRR	K-HOLRR					
					(poly)	(rbf)				
945.79	12.92	_	0.12	0.04	0.53	_				
—	235.73	75.47	121.28	100.94	0.46	0.61				
—	33.83	37.70	22.3	14.41	19.20	19.67				
—	40.23	—	2.12	1.67	1.57	1.66				
Table: Average running times in seconds										

Sample complexity analysis. Minimax lower bounds for low rank regression. Take the tensor structure of the input into account. Extend to other loss functions.

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