

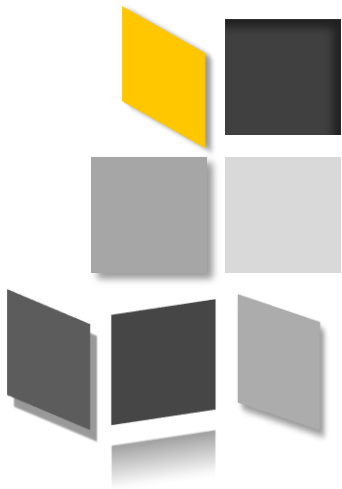
**COMP/MATH 553 Algorithmic
Game Theory
Lecture 7: Bulow-Klemperer &
VCG Mechanism**

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An overview of today's class

- 
- Prior-Independent Auctions & Bulow-Klemperer Theorem*
 - General Mechanism Design Problems*
 - Vickrey-Clarke-Groves Mechanism*



Prior-Independent Auctions

Another Critique to the Optimal Auction



- ❑ What if your distributions are *unknown*?
- ❑ When there are many bidders and enough past data, it is reasonable to assume you know exactly the value distributions.
- ❑ But if the market is “thin”, you might not be confident or not even know the value distributions.
- ❑ Can you design an auction that does not use any knowledge about the distributions but performs *almost as well as* if you know *everything* about the distributions.
- ❑ Active research agenda, called prior-independent auctions.

Bulow-Klemperer Theorem



[Bulow-Klemperer '96] For any regular distribution F and integer n .

$$\mathbb{E}_{v_1, \dots, v_{n+1}} [\text{REV}(\text{Vickrey})] \geq \mathbb{E}_{v_1, \dots, v_n} [\text{REV}(\text{Myerson})]$$

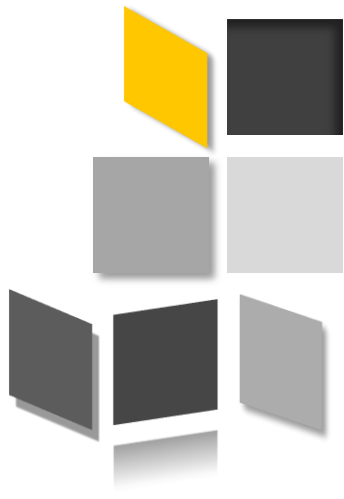
Remark:

- Vickrey's auction is prior-independent!
- This means with the same number of bidders, Vickrey Auction achieves at least $n-1/n$ fraction of the optimal revenue. (exercise)
- More competition is better than finding the right auction format.

Proof of Bulow-Klemperer



- Consider another auction M with $n+1$ bidders:
 1. Run Myerson on the first n bidders.
 2. If the item is unallocated, give it to the last bidder for free.
- This is a *DSIC* mechanism. It has the *same* revenue as Myerson's auction with n bidders.
- Notice that its allocation rule always gives out the item.
- Vickrey Auction also always gives out the item, but always to the bidder who has the highest value (also with the highest virtual value).
- Vickrey Auction has the highest virtual welfare among all DSIC mechanisms that always give out the item! □



General Mechanism Design Problem (Multi-Dimensional)

Multi-Dimensional Environment



- ❑ So far, we have focused on single-dimensional environment.
- ❑ In many scenarios, bidders have different value for different items.
 - Sotherby's Auction:



❑ Multi-Dimensional Environment

- n strategic participants/agents,
- a set of possible outcomes Ω .
- agent i has a private value $v_i(\omega)$ for each ω in Ω (abstract and could be large).

Examples of Multi-Dimensional Environment



- ❑ Single-item Auction in the single-dimensional setting:
 - $n+1$ outcomes in Ω .
 - Bidder i only has positive value for the outcome in which he wins, and has value 0 for the rest n outcomes

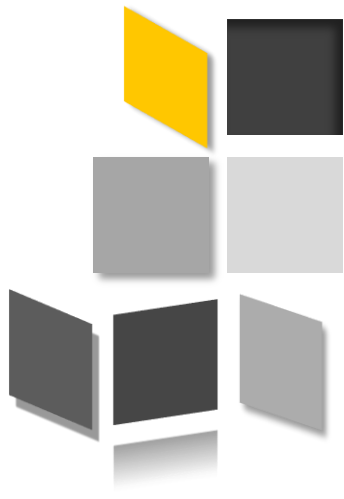
- ❑ Single-item Auction in the multi-dimensional setting:
 - Imagine you are not selling an item, but auctioning a startup who has a lot of valuable patents.
 - n companies are competing for it.
 - Still $n+1$ outcomes in Ω .
 - But company i doesn't win, it might prefer the winner to be someone in a different market other than a direct competitor.
 - So besides the outcome that i wins, i has different values for the rest n outcomes.

How do you optimize Social Welfare (Non-bayesian)?



- ❑ What do I mean by optimize social welfare (algorithmically)?
 - $\omega^* := \operatorname{argmax}_{\omega} \sum_i v_i(\omega)$

- ❑ How do you design a DSIC mechanism that optimizes social welfare.
 - Take the same two-step approach.
 - Sealed-bid auction. Bidder i submits b_i which is indexed by Ω .
 - Allocation rule is clear: assume b_i 's are the true values and choose the outcome that maximizes social welfare.
 - In single-dimensional settings, once the allocation rule is decided, Myerson's lemma tells us the unique payment rule.
 - In multi-dimensional settings, Myerson's lemma doesn't apply ... How can you define monotone allocation rule when bids are multi-dimensional?
 - Similarly, how can we define the payment rule even if we know the allocation rule.



Vickrey-Clarke-Groves (VCG) Mechanism

The VCG Mechanism



[The Vickrey-Clarke-Groves (VCG) Mechanism] In every general mechanism design environment, there is a DSIC mechanism that maximizes the social welfare. In particular the allocation rule is

$$x(b) = \operatorname{argmax}_w \sum_i b_i(w) \quad (1);$$

and the payment rule is

$$p_i(b) = \max_w \sum_{j \neq i} b_j(w) - \sum_{j \neq i} b_j(w^*) \quad (2),$$

where $w^* = \operatorname{argmax}_w \sum_i b_i(w)$ is the outcome chosen in (1).

Understand the payment rule



□ What does the payment rule mean?

- $p_i(\mathbf{b}) = \max_{\omega} \sum_{j \neq i} b_j(\omega) - \sum_{j \neq i} b_j(\omega^*)$
- $\max_{\omega} \sum_{j \neq i} b_j(\omega)$ is the optimal social welfare when i is not there.
- ω^* is the optimal social welfare outcome, and $\sum_{j \neq i} b_j(\omega^*)$ is the welfare from all agents except i .
- So the difference $\max_{\omega} \sum_{j \neq i} b_j(\omega) - \sum_{j \neq i} b_j(\omega^*)$ can be viewed as “the **welfare loss** inflicted on the other $n-1$ agents by i ’s presence”. Called “externality” in Economics.
- Example: single-item auction.
 - If i is the winner, $\max_{\omega} \sum_{j \neq i} b_j(\omega)$ is the second largest bid.
 - $\sum_{j \neq i} b_j(\omega^*) = 0$.
 - So exactly second-price.

The VCG Mechanism



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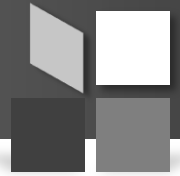
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where $w^* = \operatorname{argmax}_w \sum_i b_i(w)$ is the outcome chosen in (1).

Proof: See the board!

Discussion of the VCG mechanism



- ❑ *DSIC* mechanism that *optimizes social welfare* for *any* mechanism design problem !

- ❑ However, sometimes *impractical*.

- ❑ How do you find the allocation that maximizes social welfare. If Ω is really large, what do you do?
 - m items, n bidders, each bidder wants only one item.
 - m items, n bidders, each bidder is single-minded (only like a particular set of items).
 - m items, n bidders, each bidder can take any set of items.

- ❑ Computational intractable.

- ❑ If you use approximation alg., the mechanism is no longer DSIC.