

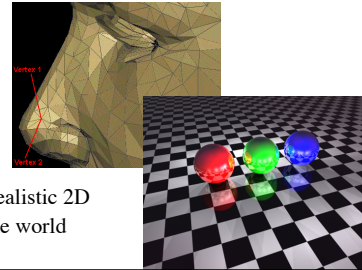
Computer graphics Ray tracing

Putting it all together

Our last real lecture!!

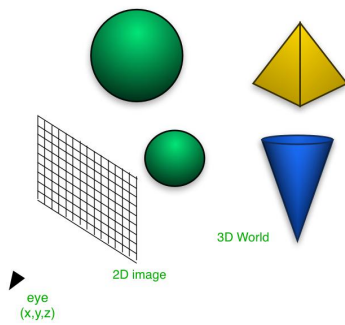
Computer Graphics Rendering

- World is represented by a set of 3D objects, with colors, reflectivity, transparency, etc.
 - Primate objects: Polygons, spheres, cones
 - Complex objects: Mesh of triangles

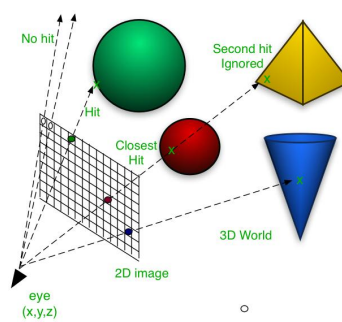


- Goal: Produce a realistic 2D picture of the world

The input



Ray-tracing



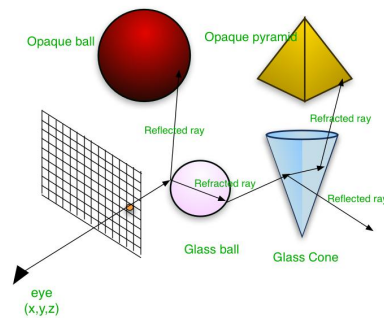
Ray-tracing algorithm

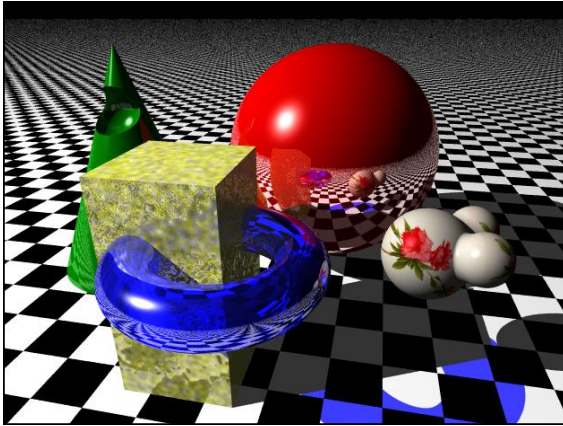
Input: - world: set of 3D objects
 - (x,y,z) position of the eye
 - Position of the 2D screen

Output: Image: array of colors of size nPixels by mPixels

For i = 1...nPixels
 For j = 1...mPixels
 r = ray(eye -> pixel(i,j))
 object = getClosestIntersection(r, world)
 if (object!=null) then
 image[I,j] = object.getColor();

Recursive Ray-tracing





Finding intersections

- Suppose your world consists of Millions of objects
- How can you calculate closest intersection quickly?
 - Computing intersection between ray and each object is much too slow
- Idea: Store your objects in a data structure that allows you to quickly discard objects that can't have intersection

Quad trees

For a 2D-world,
Subdivide the world into four quadrants.

Keep subdividing as long there is more than one object per square

For 3D-world,
Subdivide world into eight octants

Quad trees

Subdivision is represented as a tree:
Root = complete world
Children = four quadrants

Fast ray intersection problem

To quickly find intersection between ray and world:

Find which main quadrant is intersected

Find which of its subquadrant is intersected

... Keep going down the tree until a leaf is found

If leaf contains an object, test intersection

Continue until intersection is found