On a DAG Partitioning Problem

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Problem Statement

Leskovec, Backstrom, Kleinberg 2009

Given a directed acyclic graph G with arc weights,

Delete a set of arcs of minimum total weight so that each of the resulting connected components has exactly one sink.









Example





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Multiway Cut Problem



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Multiway Cut Problem



NP-hardness

Leskovec et al. proved that DAG Partitioning is NP-hard. Multiway Cut with k terminals \Rightarrow DAG Partitioning with k sinks.

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Approximation Algorithms?

Theorem (Călinescu, Karloff, Rabani 1998)

Multiway cut with k terminals is $\left(\frac{3}{2} - \frac{1}{k}\right)$ -approximable.

Theorem (Alamdari, M 2012)

For any fixed $\epsilon > 0$ there is no polynomial $(n^{1-\epsilon})$ -approximation algorithm for DAG Partitioning problem if $P \neq NP$.

Hardness result holds for DAGs with two sinks, unit weights, max outdegree 3

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A Positive Result

Theorem (Alamdari, M 2012)

The DAG Partitioning problem can be solved optimally on a DAG with bounded pathwidth.

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Two Definitions

- Unique sink property
- O The sink of a vertex

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General Structure



The Key Claim

Claim

The 3-SAT instance is satisfiable \Leftrightarrow

DAG Partitioning has a solution that does not delete any blue arcs

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The Godget for a Variable



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The Gadget for a Variable



The Godget for a Variable



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Avoiding Heavy Edges and Large Out-degrees

- 💶 two sinks
- I blue (heavy) edges
- Iarge out-degrees

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Definition of pathwidth

Definition

The family $\{W_i : 1 \le i \le m\}$ of subsets of V(G) is a path decomposition of G if it satisfies:

(i)
$$\cup_{1 \leq i \leq m} W_i = V(G)$$
.

(ii) $\forall uv \in E(G), \exists a \text{ bag containing } u \text{ and } v.$

(iii) Every $v \in V(G)$ is contained in a consecutive set of bags.

Width of the path decomposition is $\max\{|W_i|\}$.

Given a path decomposition of width k, there is an algorithm with running time $2^{O(k^2)}n$.

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The Subproblems

Alter the path decomposition so that every child is only slightly different with its parent.

The subproblems are of the form (H, X, P, F, D).

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 $H O(k^{2}n)$ X 1 $P 2^{k^{2}}$ $F 2^{k}$ $D 2^{k^{2}}$

 $2^{O(k^2)}n$ subproblems, each update in time $O(k^3)$.

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What About Treewidth?

OPEN. What about bounded-treewidth graphs!

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Thank you Slide

Thanks for your attention :-)

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