Using Linear Algebra in Algorithms Example 1: Perfect Matching

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Toy problem: finding a triangle



• Running time: $\binom{n}{3} = O(n^3) \dots$ can we do better?

Adjacency matrix

$$A = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$



Adjacency matrix and its square



 $B_{i,j} = \sum_{k=1}^{n} A_{i,k} \times A_{k,j} = number of common neighbours of i and j$

Adjacency matrix and its square





So, vertices 1 and 2 are in a triangle!

$$B_{i,j} = \sum_{k=1}^{n} A_{i,k} \times A_{k,j} = number of common neighbours of i and j$$

How fast can we find A²?

- Naïve multiplication: O(n³)
- Strassen algorithm'69: O(n^{2.81}) for multiplying two nxn matrices

(Very nice algorithm... read wikipedia or CLRS http://staff.ustc.edu.cn/~csli/graduate/algorithms/book6/chap31.htm)

 Coppersmith-Winograd'90: O(n^{2.38}) (Best known exponent is Le Gall'14: 2.3728639)

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- Coppersmith-Winograd'90: O(n^{2.38}) (Best known exponent is Le Gall'14: 2.3728639)
- Gives a running time of

 $O(n^{2.38}) + n^2 + n = O(n^{2.38})$

for finding a triangle in an n-vertex graph.

STUDENT MATHEMATICAL LIBRARY

Thirty-three Miniatures

Mathematical and Algorithmic Applications of Linear Algebra

Jiří Matoušek







چهار نمونه از کاربردهای جبرخطی در دیگر شاخههای ریاضیات

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Perfect Matching

- Perfect matching is M⊆E such that each vertex incident with *exactly* one edge in M
- Problem: find a perfect matching in a given graph!



Matching History

Dense Graphs

m=n²

Edmonds 1965 $O(n^4)$ $O(n^{2.5})$ **Even-Kariv** 1975 Micali-Vazirani 1980-1990 $O(n^{2.5})$ 1989 $O(n^{3.38})$ Rabin-Vazirani $O(n^3)$ Mucha-Sankowski 2004 $O(n^{2.38})$ 2004 Mucha-Sankowski O(n^{2.38}) 2006 Harvey

Algebraic algorithms are probabilistic: probability of correctness > 99%

Generic Matching Algorithm

If G has no perfect matching, halt For each edge *e* If *e* is contained in a perfect matching Add *e* to solution Delete endpoints of e

Generic Matching Algorithm



- How can we test this?
- Randomization and linear algebra play key role

Outline

- Implementing Generic Algorithm
 O(n^{4.38}) algorithm (4.38 = 2 + 2.38)
 - O(n^{3.38}) algorithm Rabin-Vazirani'89
 - O(n³) algorithm
 Micha-Sankowski'04
 - O(n^{2.38}) algorithm Harvey'06

Matching & Tutte Matrix

- Let G=(V,E) be a graph
- Define variable x_{uv} for each edge uv
- Define a skew-symmetric matrix T s.t.



Lemma [Tutte'47]: G has a perfect matching if and only if det(T)≠0.

This graph has no perfect matching



$$det \begin{bmatrix} 0 & -x_{1,2} & -x_{1,3} & -x_{1,4} \\ x_{1,2} & 0 & 0 & 0 \\ x_{1,3} & 0 & 0 & 0 \\ x_{1,4} & 0 & 0 & 0 \end{bmatrix} \equiv 0$$

Lemma [Tutte'47]: G has a perfect matching if and only if det(T)≠0.

This graph has a perfect matching



$$det \begin{bmatrix} 0 & -x_{1,2} & -x_{1,3} & 0 \\ x_{1,2} & 0 & 0 & 0 \\ x_{1,3} & 0 & 0 & -x_{3,4} \\ 0 & 0 & x_{3,4} & 0 \end{bmatrix} = x_{1,2}^2 x_{3,4}^2 \neq 0$$

- **Lemma** [Tutte'47]: G has a perfect matching if and only if det(T)≠0.
- Computing det(T) very slow: Contains variables, and can have exponential number of terms.
- **Lemma** [Lovász'79]: This result holds with probability 99% if we randomly choose values for $x_{\{u,v\}}$'s.
- Computing determinant of an nxn matrix of numbers can be done in time O(n^{2.38})
- O(n^{2.38}) algorithm for *deciding* a perfect matching

O(n^{4.38}) algorithm for *building* PM

Choose random values for variables and compute det (T) (Takes $O(n^{2.38})$ time) If det(T) = 0 halt For each edge uv Let U be Tutte matrix of $G - \{u, v\}$ If det(U) $\neq 0$ (Edge uv is contained in a PM) Add uv to matching Delete vertices u and v

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- **Lemma** [Tutte'47]: G has a perfect matching if and only if det(T) \neq 0.
- **Lemma** [Rabin-Vazirani'89]: G-{u,v} has a perfect matching if and only if $(T^{-1})_{u,v} \neq 0$.

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Proof:

$$T = \begin{bmatrix} 0 & -x_{1,2} & U \\ x_{1,2} & 0 & U \\ \hline V & W \end{bmatrix}$$

G-{1,2} has a perfect matching \Leftrightarrow det(W) \neq 0

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Proof:

$$T = \begin{bmatrix} 0 & -x_{1,2} & U \\ x_{1,2} & 0 & U \\ \hline V & W \end{bmatrix} \qquad T^{-1} = \begin{bmatrix} 0 & -a & \widetilde{U} \\ a & 0 & U \\ \hline \widetilde{V} & W \end{bmatrix}$$

G-{1,2} has a perfect matching \Leftrightarrow det(W) $\neq 0 \Leftrightarrow det(T) \times det \begin{bmatrix} 0 & -a \\ a & 0 \end{bmatrix} \neq 0 \Leftrightarrow a \neq 0$

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O(n^{3.38}) algorithm

Rabin-Vazirani '89

```
Choose random values for variables and
  compute det (T)
If det(T) = 0 halt
Repeat n/2 times
  Compute T<sup>-1</sup>
                                        (Takes O(n<sup>2.38</sup>) time)
  Find an edge uv with T^{-1}_{u,v} \neq 0
  Add uv to matching
                                          (Takes O(n^2) time)
  Delete u and v from G
```

O(n^{3.38}) algorithm

Rabin-Vazirani '89

Choose random values for variables and compute det (T) If det(T) = 0 halt Repeat n/2 times Compute T⁻¹ (Takes O(n^{2.38}) time) Find an edge uv with $T^{-1}_{u,v} \neq 0$ Add uv to matching (Takes $O(n^2)$ time) Delete u and v from G

- Total running time: O(n^{3.38})
- Improve: Recompute T⁻¹ quickly in each iteration?

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Quick updating lemma

 Lemma. After deleting two vertices, inverse of the new Tutte matrix can be found in time O(n²)

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• Proof.

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Sherman-Morrison-Woodbury Formula:

$$W^{-1} = \widetilde{W} - \widetilde{V} \begin{bmatrix} 0 & -a \\ a & 0 \end{bmatrix}^{-1} \widetilde{U} = \widetilde{W} - \frac{1}{a} (\widetilde{V}_2 \widetilde{U}_1 - \widetilde{V}_1 \widetilde{U}_2)$$

O(n³) algorithm

Micha-Sankowski'04

Choose random values for variables and compute det (T) If det(T) = 0 halt Compute T⁻¹ (Takes $O(n^{2.38})$ time) Repeat n/2 times Find an edge uv with $T^{-1}_{uv} \neq 0$ Add uv to matching (Takes O(n²) time) Delete u and v from G Update T⁻¹ (Takes $O(n^2)$ time)

• Total runtime: O(n³)

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(Here c=4 parts)

• Partition into *c* parts $\{V_1, \dots, V_c\}$

(arbitrarily)

For each pair of parts {V_a,V_b}
 – Recurse on G[V_a ∪ V_b]



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- Base case: 2 vertices



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 Recurse on G[V_a ∪ V_b]
- Base case: 2 vertices {u,v}
 If T⁻¹_{u,v}≠0, add {u,v} to matching, update T⁻¹

Recursion F.A.Q.

- Why not just recurse on G[V_a]?
 - Edges between parts would be missed
 - Claim: Our recursion examines every pair of vertices \Rightarrow examines every edge
- Why does algorithm work?
 It implements Rabin-Vazirani Algorithm!
- Isn't this horribly slow?
 - No: we'll see recurrence next
 - Partition into *c* parts $\{V_1, \ldots, V_c\}$
 - For each pair of parts {V_a,V_b}
 Recurse on G[V_a ∪ V_b]
 - Base case: 2 vertices {u,v}
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(arbitrarily)

Final Matching Algorithm



Final Matching Algorithm





Time Analysis

$$R(s) = \begin{pmatrix} c \\ 2 \end{pmatrix} \cdot R \begin{pmatrix} 2 \\ c \end{pmatrix} + O \begin{pmatrix} c \\ 2 \end{pmatrix} \cdot s^{\omega} \end{pmatrix}$$
• Basic Divide-and-Conquer

$$- \text{ If } \log_{c/2} \begin{pmatrix} c \\ 2 \end{pmatrix} < \omega \text{ then } R(n) = O(n^{\omega})$$
• Since $\log_{c/2} \begin{pmatrix} c \\ 2 \end{pmatrix} < 2 + \frac{1}{\log c - 1}$,

just choose *c* large enough!

c = 13 is large enough if ω = 2.38

Handling Updates



Handling Updates



Delete vertices u and v



- Delete vertices u and v \Rightarrow clear rows / columns
- Causes rank-1 updates to T⁻¹
- Algorithm still takes $\Omega(n^3)$ time

Matching Outline

- Tutte Matrix & Properties
- Rabin-Vazirani Algorithm
- Rank-1 Updates
- Rabin-Vazirani with Rank-1 Updates
- Our Recursive Algorithm (overview)
- Our Recursive Algorithm (fast updates)

Just-in-time Updates



- Don't update entire matrix!
- Just update parent in recursion tree
- Updates outside of parent are postponed

Postponed Updates



- Accumulate batches of updates
- **Claim**: New updates can be applied with matrix multiplication and inversion

Final Matching Algorithm

If base case with 2 vertices {u,v} If $T^{-1}_{u,v} \neq 0$, add {u,v} to matching Else Partition into c parts $\{V_1, \dots, V_c\}$ For each pair $\{V_a, V_b\}$ Recurse on $G[V_a \cup V_b]$ Apply updates to current subproblem

Invariant: Before / after child subproblem, parent's submatrix is completely updated \Rightarrow in every base case, T⁻¹_{u,v} is up-to-date!



Only take edges that can be extended to a **perfect matching** in the whole graph. This decision is possible because invariant ensures that $T^{-1}_{u,v}$ is up-to-date.

Matching Summary

- Theorem. We can compute a perfect matching in O(n^{2.38}) time, with correctness probability > 99%
- Algorithm uses only simple randomization, linear algebra and divide-and-conquer
- Easy to implement (200 lines of MATLAB code)
- Extensions for: (by existing techniques)
 - Maximum matching
 - Las Vegas

Conclusion

- Aim: highlight the power of linear algebra in algorithm design ... read!
- Another example tomorrow: maximum flow problem
- Easy-to-read reference for this talk: Algebraic algorithms for matching, Ivan, Virza, and Yuen https://madars.org/projects/6854/AlgMatching.pdf

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- Nick Harvey's paper is also readable: http://www.cs.ubc.ca/~nickhar/Publications/AlgebraicMatching/AlgebraicMatching.pdf

Thanks for listening

